# Automation systems Drive solutions

# Controls Inverters Motors Gearboxes Engineering Tools



# Contents of the L-force catalogue

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# Lenze makes many things easy for you.

With our motivated and committed approach, we work together with you to create the best possible solution and set your ideas in motion - whether you are looking to optimise an existing machine or develop a new one. We always strive to make things easy and seek perfection therein. This is anchored in our thinking, in our services and in every detail of our products. It's as easy as that!

# 1

# **Developing ideas**

Are you looking to build the best machine possible and already have some initial ideas? Then get these down on paper together with us, starting with small innovative details and stretching all the way to completely new machines. Working together, we will develop an intelligent and sustainable concept that is perfectly aligned with your specific requirements

# 4

# **Manufacturing machines**

Functional diversity in perfect harmony: as one of the few full-range providers in the market, we can provide you with precisely those products that you actually need for any machine task — no more and no less. Our L-force product portfolio, a consistent platform for implementing drive and automation tasks, is invaluable in this regard.

# 2

# **Drafting concepts**

We see welcome challenges in your machine tasks, supporting you with our comprehensive expertise and providing valuable impetus for your innovations. We take a holistic view of the individual motion and control functions here and draw up consistent, end-to-end drive and automation solutions for you - keeping everything as easy as possible and as extensive as necessary.

# 5

# **Ensuring productivity**

Productivity, reliability and new performance peaks on a daily basis – these are our key success factors for your machine. After delivery, we offer you cleverly devised service concepts to ensure continued safe operation. The primary focus here is on technical support, based on the excellent application expertise of our highly-skilled and knowledgeable after-sales team.

# 3

# Implementing solutions

Our easy formula for satisfied customers is to establish an active partnership with fast decision-making processes and an individually tailored offer. We have been using this simple principle to meet the ever more specialised customer requirements in the field of mechanical engineering for many years.

# A matter of principle: the right products for every application.

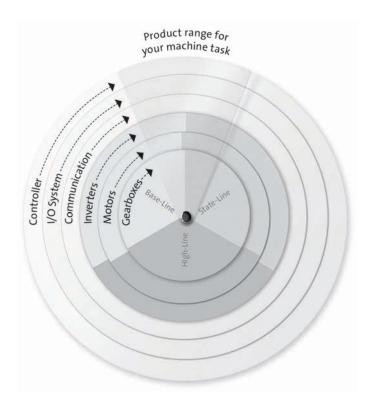
Lenze's extensive L-force product portfolio follows a very simple principle. The functions of our finely scaled products are assigned to the three lines Base-Line, State-Line or High-Line.

But what does this mean for you? It allows you to quickly recognise which products represent the best solution for your own specific requirements.

# Powerful products with a major impact:

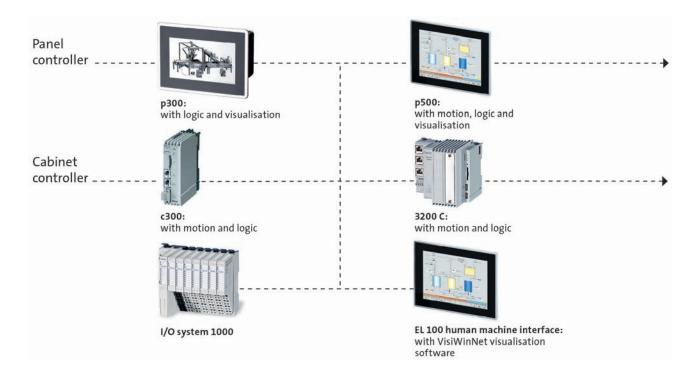
- · Easy handling
- High quality and durability
- Reliable technologies in tune with the latest developments

Lenze products undergo the most stringent testing in our own laboratory. This allows us to ensure that you will receive consistently high quality and a long service life. In addition to this, five logistics centres ensure that the Lenze products you select are available for quick delivery anywhere across the globe. It's as easy as that!

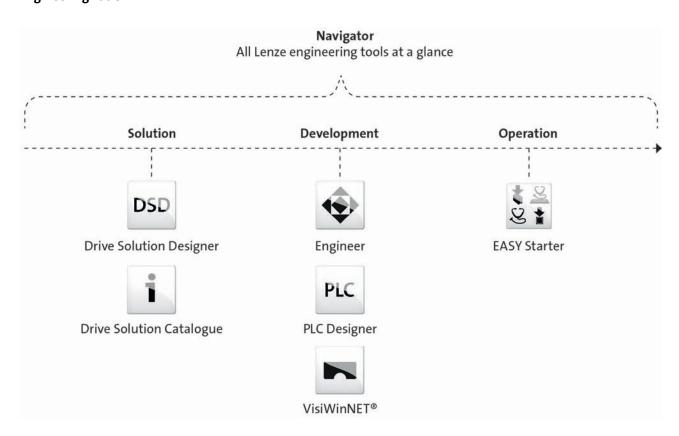


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#### **Controls**

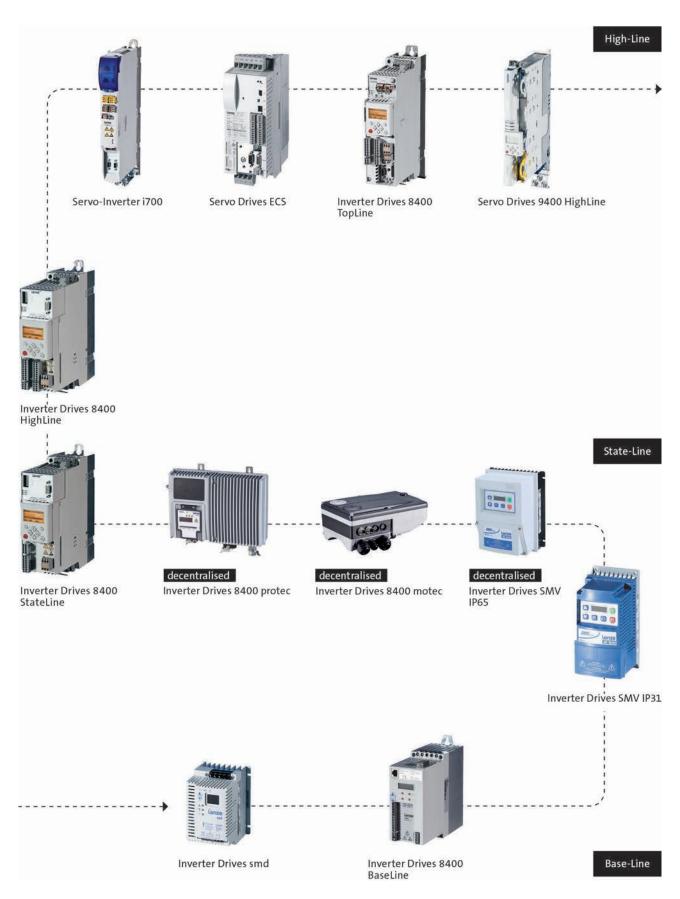


# **Engineering Tools**



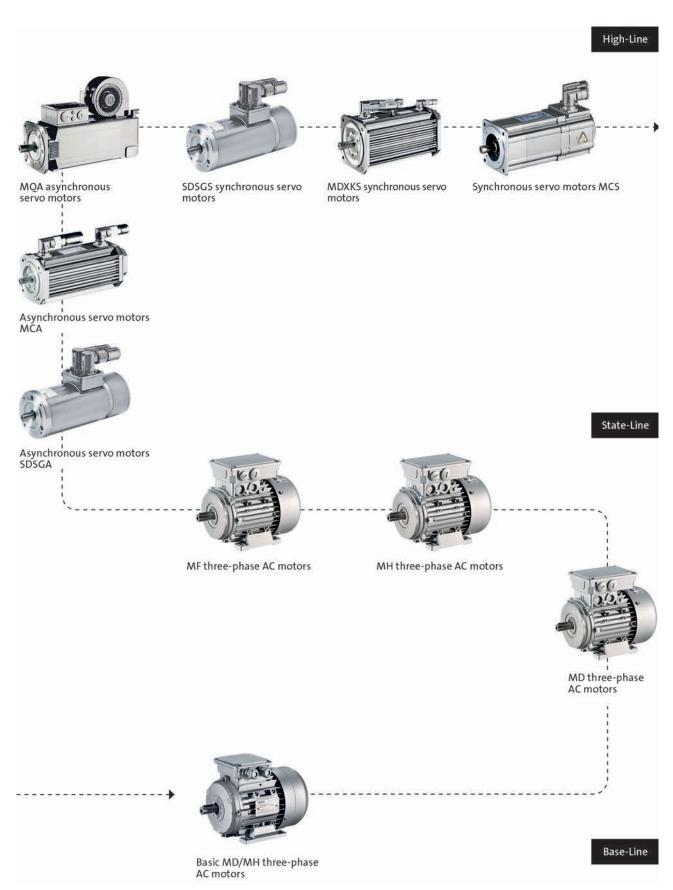
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# Inverters



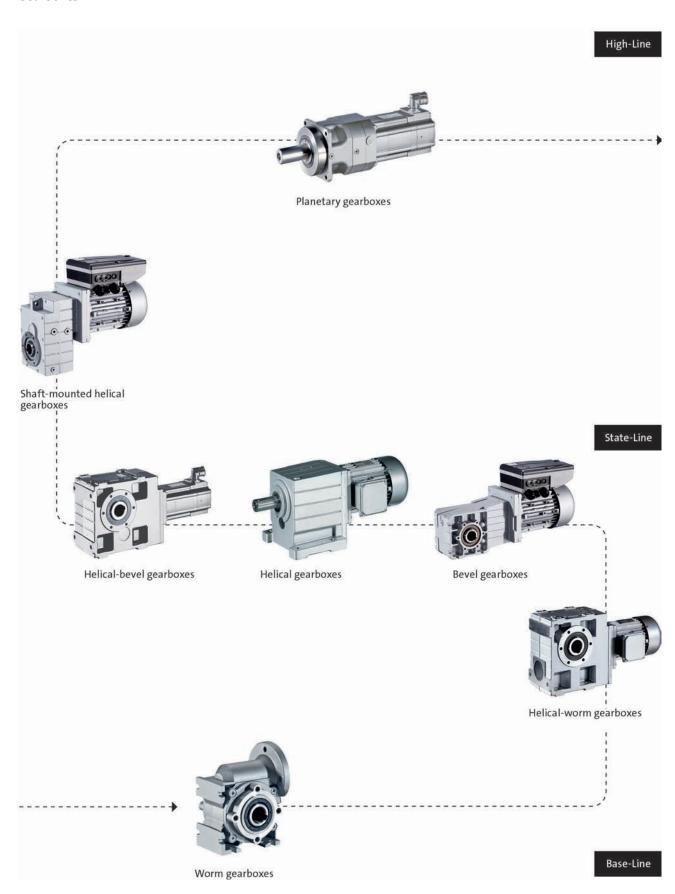
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# Motors



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# Gearboxes



0.75 to 7.5 kW



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# Inverter Drives 8400 protec

# Contents

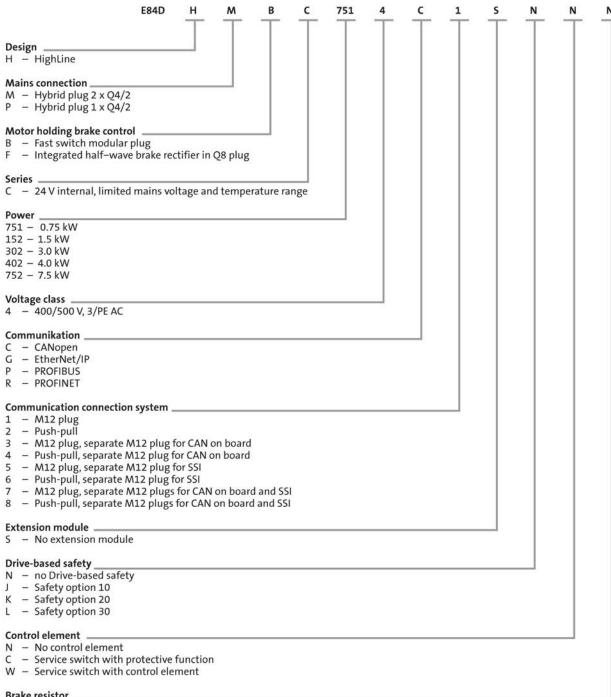


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#### General information



# **Product key**



Brake resistor

N - No brake resistor

R - Integrated brake resistor (0.75 kW and 1.5 kW devices only)

E — Connection for external brake resistor



# **Equipment**

# Display and diagnostics

Status LEDs L-force diagnostic interface



optional

# **Mains connection**

Pluggable in loopthrough technique

# Pluggable control connections

For commnication purposes and inputs/outputs

**Brake resistor** 

Plug connection

**Motor connection** 

Connection via hybrid cable

**General information** 



# **List of abbreviations**

b	[mm]	Dimensions
C <sub>th</sub>	[KWs]	Thermal capacity
f <sub>ch</sub>	[kHz]	Rated switching frequency
h	[mm]	Dimensions
I <sub>N, out</sub>	[A]	Rated output current
I <sub>N, AC</sub>	[A]	Rated mains current
m	[kg]	Mass
n <sub>max</sub>	[r/min]	Max. speed
Р	[kW]	Typical motor power
$P_V$	[kW]	Power loss
P <sub>N</sub>	[kW]	Rated power
R <sub>N</sub>	[Ω]	Rated resistance
t	[mm]	Dimensions
U <sub>AC</sub>	[V]	Mains voltage
U <sub>DC</sub>	[V]	DC supply
U <sub>N, AC</sub>	[V]	Rated voltage
U <sub>out</sub>	[V]	Max. output voltage

ASM	Asynchronous motor
DIAG	Slot for diagnostic adapter
DIN	Deutsches Institut für Normung e.V.
EN	European standard
EN 60529	Degrees of protection provided by enclosures (IP code)
EN 60721-3	Classification of environmental conditions; Part 3: Classes of environmental parameters and their limit values
EN 61800-3	Electrical variable speed drives Part 3: EMC requirements including special test methods
IEC	International Electrotechnical Commission
IEC 61508	Functional safety of electrical/electronic/program- mable electronic safety-related systems
IM	International Mounting Code
IP	International Protection Code
MCI	Slot for communication module (module communication interface)
NEMA	National Electrical Manufacturers Association
UL	Underwriters Laboratory Listed Product
UR	Underwriters Laboratory Recognized Product
VDE	Verband deutscher Elektrotechniker (Association of German Electrical Engineers)

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# 8400 protec

The wall-mounted device with a high degree of integration for complex decentralised systems. It excels through its robust design, high degree of operational reliability and fast installation.

This inverter with a high level of functionality facilitates both basic and servo-based applications. The Inverter Drives 8400 protec is supplied with all modules and interfaces ready to be connected.

#### **On-site diagnostics**

- A large display provide constant information on the operating status of the device.
- The clearly laid out LEDs provide additional diagnostics information.
   The fast diagnostics system thereby makes an effective contribution to increasing system availability.

#### Decentralised integrated positioning

- Implementing affordable and decentralised positioning applications
  with asynchronous motors. Whether switch-off, tabular or absolute
  positioning: the Inverter Drives 8400 protec offers integrated
  solutions for these applications. The ability to connect incremental
  and absolute value encoders rounds off this scope of functions.
- The parameters are set conveniently using the "L-force Engineer" here. The range also has a freely editable function block interconnection for integration of logic, arithmetic and mathematic program through graphic programming.

#### Safety engineering in line with EN ISO 13849-1

- The certified safety system enables not only the connection of local safety elements and safe communication via PROFIsafe, but also a series of safety functions.
- Safe torque off (STO)
- Safe stop 1 (SS1)
- Emergency stop (SSE)
- Safe operation mode selector (OMS)
- Safe enable switch (ES)

#### **Further benefits**

- 200% overload current (3s)
- V/f control with and without encoder
- Sensorless vector control
- · Servo control
- · Short-circuit and earth-fault protected
- DC-injection braking
- S-shaped ramp for smooth acceleration
- Max. output frequency 1,000 Hz
- 15 fixed frequencies
- Standardised connectors
- · CANopen, EtherNet/IP, PROFIBUS, PROFINET



Inverter Drives 8400 protec

**General information** 



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# **Functions and features**

Mode	
	8400 protec
Conrol types, motor control	
Sensorless vector control (SLVC)	For three-phase asynchronous motors
V/f control (VFCplus)	For three-phase AC motors and asynchronous servo motor (linear or square-law)
Basic functions	
	Freely assignable user menu Free function block interconnection with extensive function library Parameter change-over DC brake function Flying restart circuit S-shaped ramps for smooth acceleration PID controller 15 fixed frequencies Masking frequencies
Technology applications	0 14.
	Speed actuating drive Switch-off positioning without feedback Table positioning without feedback
Monitoring and protective measures	
	Short circuit Earth fault Overvoltage Motor phase failure Overcurrent I² x t-Motor monitoring Motor overtemperature Mains phase failure Protection for cyclical mains switching Motor stalling
Diagnostics	
	Data logger, logbook, oscilloscope functions
Status display	18 LEDs
Diagnostic interface	Integrated For USB diagnostic adapter or keypad (diagnosis terminal)
Braking operation	
Brake chopper	Integrated
Brake resistor 1)	Internal or external

 $<sup>^{1)}</sup>$  Internally only for 0.75 and 1.5 kW

4 1

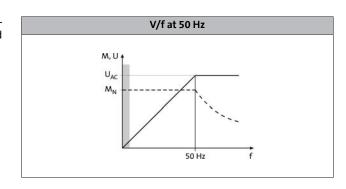
#### General information

# **Operating modes**

An inverter enables energy-efficient operation of a system in virtually all application cases. The various operating modes, which can be created by making just a few simple settings, facilitate this. The following characteristics and corresponding specifications listed on the following pages can be used to calculate the optimum operating mode during the project planning phase.

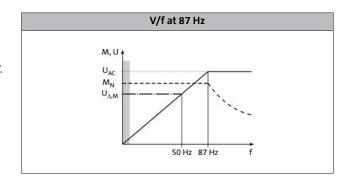
#### Standard setting

In its initial state when delivered, the inverter is set up for basic operation with a three-phase AC motor with V/f control. When operated in this mode, the rated torque of the motor is available in a setting range up to 50 Hz.



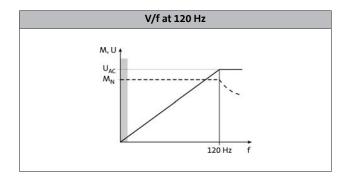
#### Extended setting range up to 87 Hz

If the V/f switchover point on the inverter is set to 87 Hz, the rated torque can be used across an extended setting range. Here, a 230/400V motor is for example used and operated in a delta layout with a 400V inverter. The setting range is then increased by 40 %. The inverter must be dimensioned for a rated motor current of 230 V.



# Operation with inverter-optimised MF motors

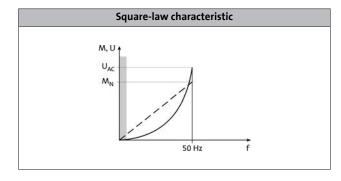
Large setting ranges and optimum operation at the rated torque: these are the strengths of the MF motor when used in combination with an inverter. The motors are optimised for a setting range up to 120 Hz. Compared to conventional 50Hz operation, the setting range increases by 250 %. It is quite simply not possible for a drive to be operated any more efficiently in a machine.



#### Operation with low loads

This operating mode can be used for various applications, e.g. for fans and pumps:

In fan and pump applications, the load behaviour follows a square-law characteristic depending on the speed. Often, an overload capacity of 120% is sufficient. This serves to operate the inverter during operation with increased power, i.e. the inverter can be dimensioned one power size smaller. The square-law characteristic which corresponds to the load behaviour can be set in the inverter.





# **Operating modes**

#### VFC-eco energy saving mode

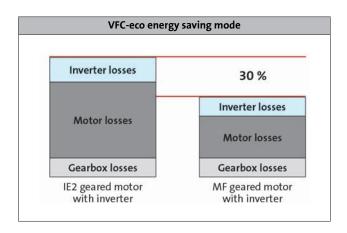
The Inverter Drives 8400 make energy saving especially easy with the "VFC eco" function. Particularly in the partial load operational range, this function significantly reduces energy requirements. Combined with the new L-force MF three-phase AC motors, this drive solution impresses with the maximum energy efficiency of a Lenze BlueGreen solution.

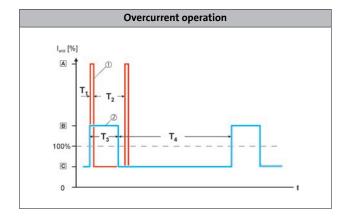
The "VFC eco" mode adjusts the magnetising current of a motor intelligently to actual requirements. This is particularly useful in partial load operational range, as this is precisely where three-phase AC motors need to be supplied with a greater magnetising current than the operating conditions actually require. The "VFC eco" mode allows losses to be reduced so much that savings of up to 30% can be achieved.

Energy efficiency can then be increased even further with the MF three-phase AC motors. These motors have been specifically designed for operation with frequency inverters. They operate at 120 Hz instead of 50 Hz, as 4-pole three-phase AC motors are at their most efficient at this frequency.

#### Overcurrent operation

The inverters can be driven at higher amperages beyond the rated current if the duration of this overcurrent operation is time limited. Two utilisation cycles with a duration of 15 s and 180 s are defined. Within these utilisation cycles, an overcurrent is possible for a certain time if afterwards an accordingly long recovery phase takes place. For both utilisation cycles, a moving average is determined separately. The adjacent diagram shows both cycles: 15 s in red and 180 s in blue. The overload times  $t_{01}$  are 3 s  $(T_1)$  and 60 s  $(T_3)$  respectively, the corresponding recovery times  $t_{re}$  are 12 s ( $T_2$ ) and 120 s ( $T_4$ ) respectively. The following tables show the resulting maximum output currents. Monitoring of the device utilisation (I x t) activates the set error response (trip or warning if one of the two utilisation values exceeds the limit of 100 %.





# **Switching frequencies**

On an inverter, the term "switching frequency" is understood to mean the frequency with which the input and outputs of the output module (inverter) are switched. On an inverter, the switching frequency can generally be set to values between 2 and 16 kHz, whereby the selection is based on the respective power output.

Since losses (in the form of heat) can be generated when switching the modules, the inverter can provide a higher output current at a switching frequency of 2 kHz. In addition to this, it is also important to differentiate between operation at a fixed switching frequency and a variable switching frequency, whereby the switching frequency is automatically reduced based on the output current here. The data for operation at increased output is permitted for operation

at a switching frequency of 2 or 4 kHz and in an ambient temperature of max. 40 °C.

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# Standards and operating conditions

Mode			
Product			8400 protec
Conformity			
CE			Low-Voltage Directive
			2006/95/EC
EAC			TP TC 004/2011 (TR C TP TC 020/2011 (TR C
Approval			
UL 508C			Power Conversion Equipment (file no. E132659)
CSA			CSA 22.2 No. 14
Degree of protection			
EN 60529			IP65 mit Bedienelement "C" IP64
NEMA 250			
Climatic conditions			
Storage (EN 60721-3-1)			1K3 (temperature: -25 °C +60 °C)
Transport (EN 60721-3-2)			2K3 (temperature: -25 °C +75 °C)
Operation (EN 60721-3-3)			3K3 (temperature: -25°C +55°C)
Current derating at over 40°C			2.5 % / K
Site altitude			
Amsl	H <sub>max</sub>	[m]	4000
Current derating at over 1000 m		[%/1000 m]	5
Vibration resistance			
Transport (EN 60721-3-2)			2M2
Operation (EN 60721-3-3)			3M4
Operation (Germanischer Lloyd)			General conditions: acceleration resistant up to 2 g

Mode	
Product	8400 protec
Supply form	
	Systems with earthed star point (TN and TT systems)
Noise emission	
EN 61800-3	Integrated RFI suppression: cable-guided, category C2 up to 20 m shielded motor cable
Insulation resistance	
EN 61800-5-1	≤ 2000 m amsl overvoltage category III
	> 2000 m amsl overvoltage category II
Degree of pollution	
EN 61800-5-1	2
Protective insulation of control circuits	
EN 61800-5-1	Safe mains isolation: double/reinforced insulation

# Technical data



# Rated data 400 V

- The data is valid for operation at 400 V AC.
  Unless otherwise specified, the data refers to the default setting.

Typical motor power					
4-pole asynchronous motor	Р	[kW]	0.75	1.50	
Product key					
Inverter			E84D === 7514 == S ==	E84D□□□1524□□S□	
Mains voltage range					
	U <sub>AC</sub>	[V]	3/PE AC 320 V-0% 440 V+0%, 45 Hz-0 % 65 Hz+0%		
Rated mains current					
	I <sub>N, AC</sub>	[A]	4.1	5.5	
Rated output current					
	I <sub>N, out</sub>	[A]	2.4	3.9	
Rated switching frequency					
	f <sub>ch</sub>	[kHz]	1	3	
Output current					
2 kHz	l <sub>out</sub>	[A]	2.4	3.9	
4 kHz	I <sub>out</sub>	[A]	2.4	3.9	
8 kHz	I <sub>out</sub>	[A]	2.4	3.9	
16 kHz	l <sub>out</sub>	[A]	1.6	2.3	

# Data for 60 s overload

Max. output current				
	I <sub>max, out</sub>	[A]	3.6	5.9
Overload time				
	t <sub>ol</sub>	[s]	60	0.0
Recovery time				
	t <sub>re</sub>	[s]	12	0.0

# Data for 3 s overload

Max. short-time output current					
	I <sub>max, out</sub>	[A]	4.8	7.8	
Overload time					
	t <sub>ol</sub>	[s]	3	3.0	
Recovery time					
	$t_{re}$	[s]	7:	5.0	



# Rated data 400 V

- The data is valid for operation at 400 V AC.
  Unless otherwise specified, the data refers to the default setting.

Typical motor power					
4-pole asynchronous motor	P	[kW]	0.75	1.50	
Product key					
Inverter			E84D === 7514 == S ==	E84D□□□1524□□S□	
Power loss					
	$P_V$	[kW]	0.066 <sup>2)</sup>	0.084 2)	
Mass					
	m	[kg]	7.6		
Max. cable length					
Shielded motor cable	I <sub>max</sub>	[m]	2	0	

# Brake chopper rated data

Rated power, Brake chopper				
	P <sub>N</sub>	[kW]	0.9	2.0
Max. output power, Brake chopper				
	P <sub>max, 1</sub>	[kW]	3.	5
Min. brake resistance				
	R <sub>min</sub>	[Ω]	150	0.0

### **Dimensions**

Dimensions			
Height	h	[mm]	260 <sup>3)</sup>
Width	b	[mm]	353
Depth	t	[mm]	110

 $<sup>^{1)}</sup>$  Technically possible cable lengths, irrespective of EMC requirements  $^{2)}$  Operation at rated output current  $\mathsf{I}_{N,\,\text{out}}.$   $^{3)}$  + 30 mm with connector shell.

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# Technical data



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# Rated data 400 V

- The data is valid for operation at 400 V AC.
- Unless otherwise specified, the data refers to the default setting.

Typical motor power						
4-pole asynchronous motor	Р	[kW]	3.00	4.00	7.50	
Product key						
Inverter			E84D□□□3024□□S□	E84D□□□4024□□S□	E84D□□□7524□□S□	
Mains voltage range						
	U <sub>AC</sub>	[V]	3/PE AC 320	V-0% 440 V+0%, 45 Hz-0 %	65 Hz+0%	
Rated mains current						
	I <sub>N, AC</sub>	[A]	9.7	12.9	20.8	
Rated output current						
	I <sub>N, out</sub>	[A]	7.3	9.5	16.0	
Rated switching frequency						
	f <sub>ch</sub>	[kHz]	8			
Output current						
2 kHz	l <sub>out</sub>	[A]	7.3	9.5	16.0	
4 kHz	l <sub>out</sub>	[A]	7.3 9.5 16.0		16.0	
8 kHz	l <sub>out</sub>	[A]	7.3	7.3 9.5 16.0		
16 kHz	l <sub>out</sub>	[A]	4.9	6.3	10.7	

# Data for 60 s overload

Max. output current					
	I <sub>max, out</sub>	[A]	11.0	14.3	19.0
Overload time					
	t <sub>ol</sub>	[s]		60.0	
Recovery time					
	t <sub>re</sub>	[s]		120.0	

# Data for 3 s overload

Max. short-time output current					
	I <sub>max, out</sub>	[A]	14.6	19.0	32.0
Overload time					
	t <sub>ol</sub>	[s]		3.0	
Recovery time					
	$t_{re}$	[s]		75.0	

4.1

Technical data

# Rated data 400 V

- The data is valid for operation at 400 V AC.
  Unless otherwise specified, the data refers to the default setting.

Typical motor power						
4-pole asynchronous motor	Р	[kW]	3.00	4.00	7.50	
Product key						
Inverter			E84D□□□3024□□S□	E84D□□□4024□□S□	E84D□□□7524□□S□	
Power loss						
	$P_V$	[kW]	0.1	.5 <sup>2)</sup>	0.23	
Mass						
	m	[kg]	11.3			
Max. cable length						
Shielded motor cable	I <sub>max</sub>	[m]		50		

# Brake chopper rated data

Rated power, Brake chopper				
	P <sub>N</sub>	[kW]	3.9	5.2
Max. output power, Brake chopper				
	P <sub>max, 1</sub>	[kW]	11	2
Min. brake resistance				
	R <sub>min</sub>	[Ω]	47	.0

### Dimensions

Dimensions			
Height	h	[mm]	260 <sup>3)</sup>
Width	b	[mm]	434
Depth	t	[mm]	148

 $<sup>^{1)}</sup>$  Technically possible cable lengths, irrespective of EMC requirements  $^{2)}$  Operation at rated output current  $\mathsf{I}_{N,\,\text{out}}.$   $^{3)}$  + 30 mm with connector shell.

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#### Technical data



#### **Mains connection**

- ▶ The mains fuse and cable cross-section specifications are for a mains connection of 3  $\times$  400 V.
- Class gG/gl fuses or class gRL semiconductor fuses.
- The cable cross-sections apply to PVC-insulated copper cables.
   Use for installation with UL-approved cables, fuses and brackets.

Typical mo- tor power	Mains voltage	Product key	Circuit breaker	Fuse		Mains connection
4-pole asyn- chronous motor		Inverter		EN 60204-1	UL	Cross-section (without mains choke)
Р	U <sub>AC</sub>		I	I	I	q
[kW]	[V]		[A]	[A]	[A]	[mm2]
0.75		E84D□□□7514□□S□				
1.50	2.46.220	E84D□□□1524□□S□	C16	16	15	2.5
3.00	3 AC 320 440	E84D ====================================				
4.00		E84D□□□4024□□S□		20	20	4.0
7.50		E84D ==== 7524 === S ==	C20			

#### **Motor connection**

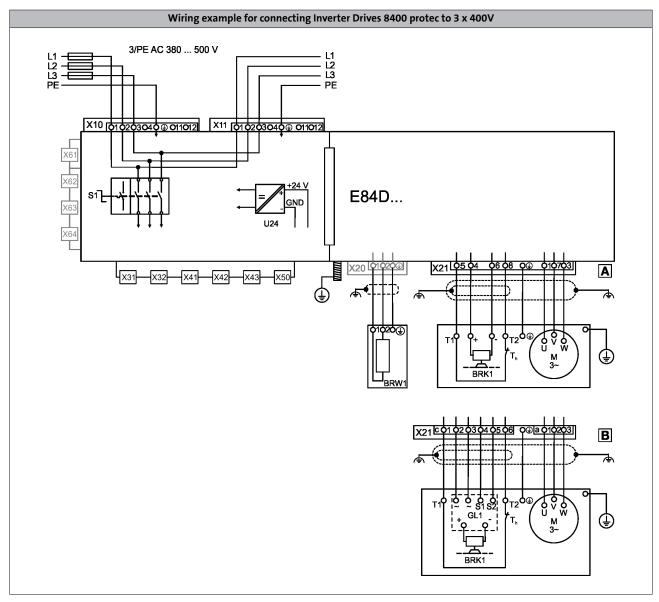
- ► Keep motor cables as short as possible, as this has a positive effect on the drive behaviour.
- With group drives (multiple motors on one inverter), the resulting cable length is the key factor. This can be calculated using the hardware manual.
- Electric strength of the motor cable: 1 kV as per VDE 250-1.

Typical mo- tor power	Mains voltage	Product key	Max. cable length		
4-pole asynchron- ous motor		Inverter	shielded C2 without external measures	shielded C2 with external measures	
Р	U <sub>AC</sub>		I <sub>max</sub>	I <sub>max</sub>	
[kW]	[V]		[m]	[m]	
0.75		E84D === 7514 == S			
1.50		E84D□□□1524□□S□			
3.00	3 AC 320 440	E84D□□□3024□□S□	20	20	
4.00		E84D□□□4024□□S□			
7.50		E84D□□□7524□□S□			

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# **Connection diagrams**



- [A] Motor connection system: connector type Q8/0 [B] Motor connection system: modular connector type

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Technical data



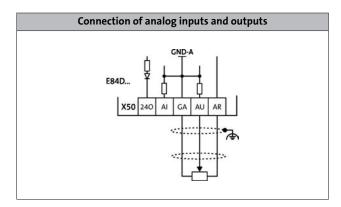
# **Control connections**

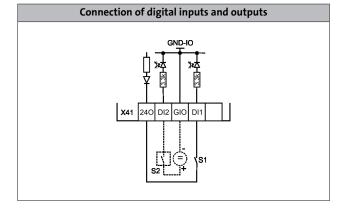
Mode						
Product	8400 protec					
Analog inputs						
Number	1 Optional: voltage or current input					
Resolution	10 bits					
Value range	0 10 V, 0/4 20 mA					
Digital inputs						
Number	6 or 4 (configurable)					
Switching level	PLC (IEC 61131-2)					
Max. input current	11 mA					
Function						
Digital outputs						
Number	0 or 2 (configurable)					
Switching level	PLC (IEC 61131-2)					
Max. output current	200 mA per output					
Relay						
Number						
Contact						
AC connection						
DC connection						
External 24 V DC supply						
	To support communication when the 400 V is switched off					
Internal 24 V DC supply						
	Max. 1 A for inputs/outputs and sensor feeds					
Interfaces						
CANopen	on board optional					
Extensions	Integrated fieldbus communication					
Safety engineering	1-2 safe inputs for passive/active actuators/PROFIsafe/PROFIsafe, depending on the safety option selected					
Drive interface						
Encoder input	Via 2 digital inputs, HTL, 2-track, 10 kHz 100 kHz, can also be used as a frequency input, SSI input (instead of analog input),					

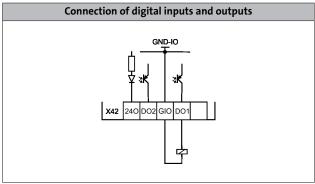
4.1



# **Control connections**







. .

Technical data







# Memory module

All drive settings for the 8400 are stored on the memory module, which is a pluggable memory chip. The memory module ensures that drives can be replaced quickly and without errors being made.

Mode	Features	Product key
Memory module	For 8400 StateLine, HighLine, Topline and protec     Packaging unit: 5 items	E84AYM10S/M

## Safety engineering

The following safety functions are integrated into the communication modules depending on the device version:

## Safety option 10

- Safe torque off (STO)
- The drive is safely disconnected when a request is sent via connected active or passive sensors

#### Safety option 20

- Safe torque off (STO)
- Safety stop 1 (SS1)
- Safe stop emergency (SSE)
- Safe operation mode selector (OMS)
- Safe enable switch (ES)
- The drive is safely disconnected by a higher-level safety PLC by means of PROFIsafe/PROFINET

# Safety option 30

- Safe torque off (STO)
- Safe stop 1 (SS1)
- Safe stop emergency (SSE)
- Safe operation mode selector (OMS)
- Safe enable switch (ES)
- The drive is safely disconnected by a higher-level safety PLC by means of PROFIsafe/PROFINET and via connected active or passive sensors

Safety functions			
Basic error limit (at 25 °C)	10	20	30
Certification			
EN ISO 13849-1	Category 4 / PLe	Categor	y 3 / PLe
EN 61800-5-2	SIL 3		
EN 62061	SIL 3		
IEC 61508		SIL 3	
Fail-safe state			
		Safe torque off	

# **Communication modules**

Inverter Drives 8400 protec are supplied with permanently installed communication modules. As well as containing the components for fieldbus communication, these modules also include the digital inputs and outputs. An analog input or a synchronous serial interface (SSI) can also be provided as an option.

#### Overview

	Digital inputs	Digital outputs	Analog inputs
Communication module	Number	Number	Number
CANopen	6 or 4 (configurable)	0 or 2 (configurable)	11)
EtherNet/IP	6 or 4 (configurable)	0 or 2 (configurable)	1 1)
PROFIBUS	6 or 4 (configurable)	0 or 2 (configurable)	11)
PROFINET	6 or 4 (configurable)	0 or 2 (configurable)	11)

<sup>&</sup>lt;sup>1)</sup> Or as a synchronous serial interface (SSI).

# Modules



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# **Communication module: CANopen**

The CANopen communication module allows the 8400 protec to be controlled via the "CANopen" bus system using digital control signals. It is integrated in the inverter with the product key E84D

The benefits of this system include:

- Easy, yet very powerful bus system
- Easy system integration, as a wide range of sensors and actuators is available in the market.

Mode	Features				
Communication module					
CANopen	Addressing via DIP switches or parameters				

Technical data

Mode					
Communication module			CANanan		
Communication module			CANopen		
Medium			DIN ISO 11898		
Communication profile			CANopen, DS301 V4.02 Lenze system bus		
Device profile			Lenze device control		
Baud rate					
	b	[kBit/s]	20 50 125 250 500 800 1000		
Node					
			Slave Multi-master		
Network topology					
			Line with terminating resistors (120 ohm) at both ends		
Number of logical process data channels			4 (each with 1 - 8 bytes)		
Number of logic parameter data channels			+(cacii with 1 0 bytes)		
			5		
Number of bus nodes					
			63		
Max. cable length					
per bus segment	I <sub>max</sub>	[m]	17 for 1000 kbps 40 for 800 kbps 110 for 500 kbps 290 for 250 kbps 630 for 125 kbps 1500 for 50 kbps 3900 for 20 kbps 8000 for 10 kbps		

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#### Modules



# EtherNet/IP communication module

The EtherNet/IP communication module based on standard TCP and UDP enables the Inverter Dives 8400 motec to support a continuous communication from the field level right through to the controlling system. The product key E84D

indicates an inverter with an integrated communication module The benefits of this system include:

- Currently widespread fieldbus based on real-time Ethernet
- Supports DHCP and BootP in allocating the IP address
- Devices linked via EtherNet/IP can be implemented seamlessly and with minimum configuration expense via mapping into the I/O tree of the RSLogix programming tool

Mode	Features
Communication module	
EtherNet/IP	Supports multicast messages, UCMM, ACD, BOOTP/DHCP, VLAN-Tagging/DSCP

## **Technical data**

Mode			
Communication module			EtherNet/IP
Communication			
Medium			CAT5e S/FTP according to ISO/ICE11801 / EN50173
Communication profile			EtherNET/IP, AC Drive
Baud rate			
	b	[MBit/s]	10/100 (full duplex/half duplex)
Node			
			Slave (Adapter)
Network topology			
			Tree, star and line
Process data words (PCD)			
16 Bit			1 16
Number of bus nodes			
			max. 254 im Subnetz
Max. cable length			
between two nodes	I <sub>max</sub>	[m]	100

# Modules



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# **PROFIBUS communication modules**

With the PROFIBUS communication module, the 8400 protec supports the most widespread current fieldbus system. It is integrated in the inverter with the product key E84D

The benefits of this system include:

- · Widespread and very powerful fieldbus system
- Integrated I/O node. Capable of communication and reading inputs even when the 400V supply is switched off.

Mode	Features
Communication module	
PROFIBUS	<ul> <li>DPVO: basic functionalities such as cyclical data exchange and diagnostics</li> <li>DPV1: supports acyclical data exchange for parameter setting, operation and alarm handling</li> </ul>

**Technical data** 

Mode			
Communication module			PROFIBUS
Communication			
Medium			RS 485
Communication profile			PROFIBUS-DP-V1 PROFIBUS-DP-V0
Device profile			PROFIDrive, version 3
Baud rate			
	b	[kBit/s]	9.6 12 000 (automatic detection)
Node			
			Slave
Network topology			
			with repeater: line or tree without repeater: line
Process data words (PCD)			
16 Bit			116
DP user data length			
			Optional parameter channel (4 words) + process data words
Number of bus nodes			
			31 slaves + 1 master per bus segment With repeaters: 125
Max. cable length			
per bus segment	I <sub>max</sub>	[m]	1200 (depending on the baud rate and the cable type used)

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#### Modules

#### **PROFINET** communication modules

With the PROFINET communication module, the 8400 protec supports a fieldbus system for continuous communication from the field level right through to company management level. It is integrated in the inverter with the product key E84D  $\square$   $\square$   $\square$   $\square$   $\square$   $\square$ 

The benefits of this system include:

- Fieldbus system capable of handling large data volumes
- Use of IT standards
- Integrated switch allows direct looping of PROFINET via the inverters
- Integrated I/O node. Capable of communication and reading inputs even when the 400V supply is switched off.

Mode	eatures					
Communication module						
PROFINET	<ul> <li>Automatic detection of the 100 Mbps baud rate</li> <li>Creation of a line topology through integrated 2-port switch</li> <li>Support for I&amp;M 0 to 4 functionality for identification of the standard device</li> <li>Link / Activity</li> </ul>					

#### **Technical data**

Mode			
Communication module			PROFINET
Communication			
Medium			CAT5e S/FTP according to ISO/ICE11801 (2002)
Communication profile			PROFINET RT Conf. Class B
Baud rate			
	b	[MBit/s]	10/100
Node			
			Slave (Device)
Network topology			
			Tree, star and line
Number of logical process data channels			
			1 ring as client (media redundancy)
Process data words (PCD)			
16 Bit			1 16
Max. cable length			
between two nodes	I <sub>max</sub>	[m]	100

Modules



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#### **Brake resistors**

An external brake resistor is required to brake high moments of inertia or in the event of prolonged operation in generator mode; this resistor converts braking energy into heat.

The brake resistors recommended in the table below have been dimensioned for approx. 1.5 times the regenerative power, with a cycle time of 15/135 s (brake/rest ratio). These brake resistors generally meet the usual requirements of standard applications.

The brake resistors are fitted with a thermostat (potential-free NC contact).



**Brake resistor** 

Typical mo- tor power	Mains voltage	Product l	key	Rated resist- ance	Rated power	Thermal capacity	Dimensions	Mass
4-pole asynchron- ous motor		Inverter	Brake resistor					
Р	U <sub>AC</sub>			R <sub>N</sub>	P <sub>N</sub>	C <sub>th</sub>	hxbxt	m
[kW]	[V]			[Ω]	[kW]	[KWs]	[mm]	[kg]
0.75		E84D000751400S0	ERBS240R300W	240.0	300.0	45.0	382 x 124 x 122	2.0
1.50		E84D00152400S0	ERBS180R350W	180.0	350.0	53.0	382 X 124 X 122	2.0
3.00	3 AC 320 440	E84D = 3024 = 5						
4.00	110	E84D = 4024 = 5	ERBS047R400W	47.0	400.0	60.0	400 x 110 x 105	2.3
7.50		E84D□□□7524□□S□						

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4.1

USB diagnostic adapter

The operation, parameter setting and diagnostics of the Inverter Drives 8400 and the Servo Drives 9400 via the L-force diagnostics is made with the keypad X400 or a PC. The connection of a PC can be made via a USB interface and the USB diagnostic adapter.

For connecting the USB diagnostic adapter with the L-force diagnostics interface (DIAG) tat the inverter, three different connecting cables are separately available in the lengths 2.5 m, 5 m and 10 m. The connection can be established during operation. The engineering tools EASY Starter or Engineer can be used to carry out the operation, parameter setting or diagnostics of the inverters. Both tools have simple intuitive surfaces. This enables a quick and easy commissioning.

Optionally to the USB diagnostic adapter, the PC system bus adapter can be used. For this purpose, a CANopen interface must be available at the inverter.



USB diagnostic adapter incl. connecting cable to the PC

► The engineering tools EASY Starter or Engineer are used for operation, parameter setting and diagnostics of the inverters.

Mode	Features	Product key
USB diagnostic adapter	<ul> <li>Input-side voltage supply via USB connection on PC</li> <li>Output-side voltage supply via inverter's diagnostic interface</li> <li>Diagnostic LEDs</li> <li>Electrical isolation of PC and inverter</li> <li>Hot-pluggable</li> </ul>	E94AZCUS

#### Connecting cables for USB diagnostic adapter

Mode	Features	Product key
	• Length: 2.5 m	EWL0070
Connecting cable for USB diagnostic adapter	Length: 5 m	EWL0071
	Length: 10 m	EWL0072

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#### **Diagnosis terminal**

The diagnosis terminal can be used as an alternative to a PC if you are looking for an easy way to operate the inverter, set parameters or carry out diagnostics locally. The structured menus and plain text display provide quick access to data.

The diagnosis terminal can be plugged into the inverter's L-force diagnostic interface (DIAG) from the outside.



Diagnosis terminal

Mode	Features	Slot	Product key
Diagnosis terminal	<ul> <li>Diagnosis terminal inside robust housing</li> <li>incl. 2.5 m cable</li> <li>Degree of protection IP20</li> <li>For 8400 motec and protec.</li> </ul>	DIAG	EZAEBK2003

#### Switch/potentiometer unit

The switch/potentiometer unit is fitted directly to the 8400 motec or in a different position within the system. An analogue setpoint can be specified with the switch/potentiometer unit and the control connections integrated in the inverter by using the integrated potentiometer; the rotary switch can, for example, be used to start/stop the drive or change the direction of rotation.

The switch/potentiometer unit is supplied with a 2.5 m connection cable



Switch/potentiometer unit

Mode	Product key
Switch/potentiometer unit (IP65)	E82ZBU

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Accessories



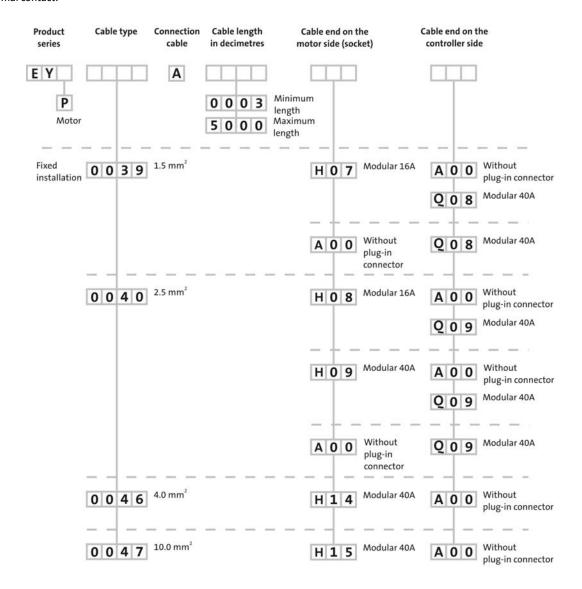
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#### System cables

For connection of the motor, Lenze provides finished hybrid cables. They are optimally matched to the connection between the Drive Package components. Motor connection, blower connection, brake connection and temperature monitoring are integrated in the cables. Cables up to a length of 100 m can be selected in increments of 0.1 m.

#### 10-pole cables

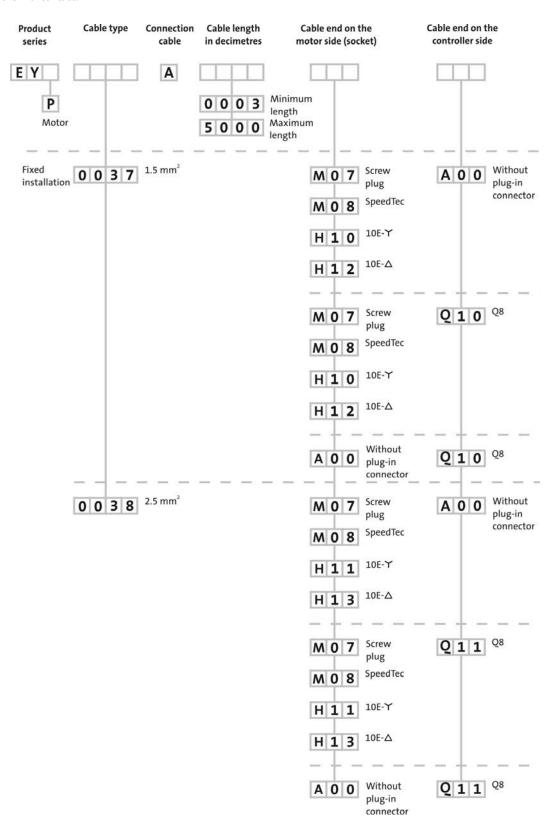
Available with cross-sections 1.5  $^2$  and 2.5  $^2$  with connection for brake or thermal contact.



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#### 8-pole cables

Available with cross-sections 1.5 $^2$  and 2.52  $^2$  with connection for brake and thermal contact.



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Accessories



4.1 - 32

0.37 to 7.5 kW



#### 4

#### Inverter Drives 8400 motec

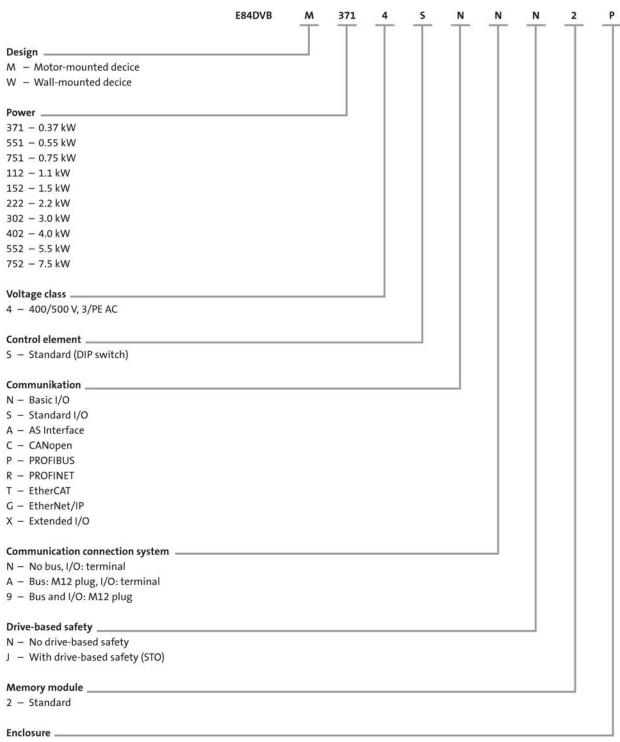
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#### **Product key**

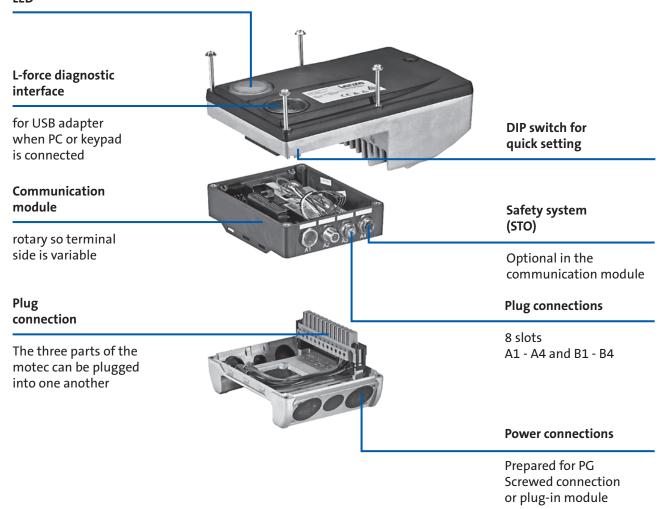


P - Enclosure IP65

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#### **Equipment**

#### Status display LED



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**General information** 



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#### **List of abbreviations**

b	[mm]	Dimensions
C <sub>th</sub>	[KWs]	Thermal capacity
f <sub>ch</sub>	[kHz]	Rated switching frequency
h	[mm]	Dimensions
I <sub>N, out</sub>	[A]	Rated output current
I <sub>N, AC</sub>	[A]	Rated mains current
m	[kg]	Mass
n <sub>max</sub>	[r/min]	Max. speed
P	[kW]	Typical motor power
$P_V$	[kW]	Power loss
P <sub>N</sub>	[kW]	Rated power
R <sub>N</sub>	[Ω]	Rated resistance
t	[mm]	Dimensions
U <sub>AC</sub>	[V]	Mains voltage
U <sub>DC</sub>	[V]	DC supply
U <sub>N, AC</sub>	[V]	Rated voltage
U <sub>out</sub>	[V]	Max. output voltage

ASM	Asynchronous motor		
DIAG	Slot for diagnostic adapter		
DIN	Deutsches Institut für Normung e.V.		
EN	European standard		
EN 60529	Degrees of protection provided by enclosures (IP code)		
EN 60721-3	Classification of environmental conditions; Part 3: Classes of environmental parameters and their limit values		
EN 61800-3	Electrical variable speed drives Part 3: EMC requirements including special test methods		
IEC	International Electrotechnical Commission		
IEC 61508	Functional safety of electrical/electronic/program- mable electronic safety-related systems		
IM	International Mounting Code		
IP	International Protection Code		
MCI	Slot for communication module (module communication interface)		
NEMA	National Electrical Manufacturers Association		
UL	Underwriters Laboratory Listed Product		
UR	Underwriters Laboratory Recognized Product		
VDE	Verband deutscher Elektrotechniker (Association of German Electrical Engineers)		

1 2



#### 8400 motec

The Inverter Drives 8400 motec excel through the greatest possible user-friendliness during operation and installation.

Particularly when used for "basic applications", the Inverter Drives 8400 motec is able to demonstrate its exemplary efficiency with regard to costs, space, time and energy

#### Cost advantages

- The easiest commissioning processes via DIP switch and potentiometer settings
- Reduced energy requirements thanks to energy-saving functionalities in combination with the geared motors from Lenze

#### Space savings

- Integrated safety and fieldbus communication tailored to individual requirements
- Modular structure minimises your spare parts inventory

#### Time savings

- Reduction in assembly and installation times through pluggable connection system: "Unpack – plug in and use!"
- Easy replacement of the memory module simplifies standard setup and increases availability

#### **Energy efficiency**

- The "VFC eco" mode offers intelligent adjustment of the magnetising current
- · Energy savings of up to 30% in partial load operation

#### **Further advantages**

- 200% overload current (3s)
- · V/f control with and without encoder
- · Sensorless vector control
- · Short-circuit and earth-fault protected
- DC-injection braking
- S-shaped ramp for smooth acceleration
- · Max. output frequency 500 Hz
  - 3 fixed frequencies
- CANopen, PROFIBUS, PROFINET, EtherCAT®, EtherNet/IP and AS-Interface
- · STO safety function

#### Sympathetically easy

 The large LED display, which can still be read from great distances, displays the status during operation and uses various flashing sequences to provide information on error causes. This keeps diagnostics easy to understand

#### Mechanically and electrically robust

 Thanks to the high degree of protection (IP65), ideally suited for use in the harshest environments.

#### A win for decentralised applications

 The 8400 motec meets all requirements of a modern, universally deployable and cost-efficient motor inverter. This makes it ideally suited for decentralised duties in the field of intralogistics, such as at airports or distribution centres.



Inverter Drives 8400 motec

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**General information** 



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#### **Functions and features**

Mode		
	8400 motec	
Conrol types, motor control		
Sensorless vector control (SLVC)	For three-phase asynchronous motors	
V/f control (VFCplus)	For three-phase AC motors and asynchronous servo motor (linear or square-law)	
Energy saving function (VFC eco)	For three-phase asynchronous motors	
Basic functions		
	Freely assignable user menu	
	Parameter change-over	
	DC brake function	
	Flying restart circuit S-shaped ramps for smooth acceleration	
	PID controller	
	3 fixed frequencies	
	Masking frequencies	
Technology applications		
	Speed actuating drive	
	Switch-off positioning without feedback	
Monitoring and protective measures		
	Short circuit	
	Earth fault	
	Overvoltage	
	Motor phase failure	
	Overcurrent  ² x t-Motor monitoring	
	Motor overtemperature	
	Mains phase failure	
	Protection for cyclical mains switching	
	Motor stalling	
Diagnostics		
	Data logger, logbook	
Status display	1 LEDs	
Diagnostic interface	Integrated	
	For USB diagnostic adapter or keypad (diagnosis terminal)	
Braking operation		
Brake chopper	Integrated	
Brake resistor	Built-on module or external	

4 2

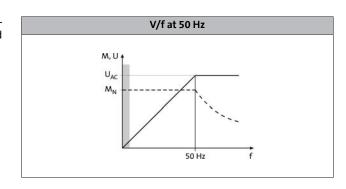
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#### **Operating modes**

An inverter enables energy-efficient operation of a system in virtually all application cases. The various operating modes, which can be created by making just a few simple settings, facilitate this. The following characteristics and corresponding specifications listed on the following pages can be used to calculate the optimum operating mode during the project planning phase.

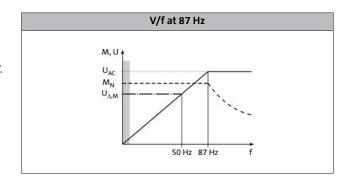
#### Standard setting

In its initial state when delivered, the inverter is set up for basic operation with a three-phase AC motor with V/f control. When operated in this mode, the rated torque of the motor is available in a setting range up to 50 Hz.



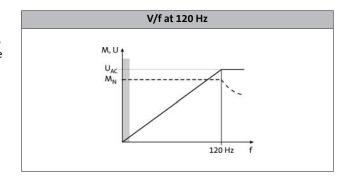
#### Extended setting range up to 87 Hz

If the V/f switchover point on the inverter is set to 87 Hz, the rated torque can be used across an extended setting range. Here, a 230/400V motor is for example used and operated in a delta layout with a 400V inverter. The setting range is then increased by 40 %. The inverter must be dimensioned for a rated motor current of 230 V.



#### Operation with inverter-optimised MF motors

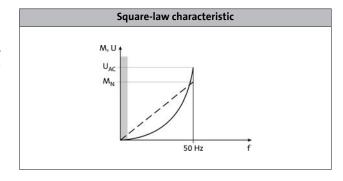
Large setting ranges and optimum operation at the rated torque: these are the strengths of the MF motor when used in combination with an inverter. The motors are optimised for a setting range up to 120 Hz. Compared to conventional 50Hz operation, the setting range increases by 250 %. It is quite simply not possible for a drive to be operated any more efficiently in a machine.



#### Operation with low loads

This operating mode can be used for various applications, e.g. for fans and pumps:

In fan and pump applications, the load behaviour follows a square-law characteristic depending on the speed. Often, an overload capacity of 120% is sufficient. This serves to operate the inverter during operation with increased power, i.e. the inverter can be dimensioned one power size smaller. The square-law characteristic which corresponds to the load behaviour can be set in the inverter.



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GEO!

#### **Operating modes**

#### VFC-eco energy saving mode

The Inverter Drives 8400 make energy saving especially easy with the "VFC eco" function. Particularly in the partial load operational range, this function significantly reduces energy requirements. Combined with the new L-force MF three-phase AC motors, this drive solution impresses with the maximum energy efficiency of a Lenze BlueGreen solution.

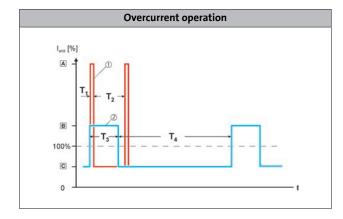
The "VFC eco" mode adjusts the magnetising current of a motor intelligently to actual requirements. This is particularly useful in partial load operational range, as this is precisely where three-phase AC motors need to be supplied with a greater magnetising current than the operating conditions actually require. The "VFC eco" mode allows losses to be reduced so much that savings of up to 30% can be achieved.

Energy efficiency can then be increased even further with the MF three-phase AC motors. These motors have been specifically designed for operation with frequency inverters. They operate at 120 Hz instead of 50 Hz, as 4-pole three-phase AC motors are at their most efficient at this frequency.

#### Overcurrent operation

The inverters can be driven at higher amperages beyond the rated current if the duration of this overcurrent operation is time limited. Two utilisation cycles with a duration of 15 s and 180 s are defined. Within these utilisation cycles, an overcurrent is possible for a certain time if afterwards an accordingly long recovery phase takes place. For both utilisation cycles, a moving average is determined separately. The adjacent diagram shows both cycles: 15 s in red and 180 s in blue. The overload times  $t_{ol}$  are 3 s  $(T_1)$  and 60 s  $(T_3)$  respectively, the corresponding recovery times  $t_{re}$  are 12 s  $(T_2)$  and 120 s  $(T_4)$  respectively. The following tables show the resulting maximum output currents. Monitoring of the device utilisation (I x t) activates the set error response (trip or warning if one of the two utilisation values exceeds the limit of 100 %.

# Inverter losses Motor losses Gearbox losses IE2 geared motor with inverter MF geared motor with inverter MF geared motor with inverter



#### **Switching frequencies**

On an inverter, the term "switching frequency" is understood to mean the frequency with which the input and outputs of the output module (inverter) are switched. On an inverter, the switching frequency can generally be set to values between 2 and 16 kHz, whereby the selection is based on the respective power output.

Since losses (in the form of heat) can be generated when switching the modules, the inverter can provide a higher output current at a switching frequency of 2 kHz. In addition to this, it is also important to differentiate between operation at a fixed switching frequency and a variable switching frequency, whereby the switching frequency is automatically reduced based on the output current here. The data for operation at increased output is permitted for operation

at a switching frequency of 2 or 4 kHz and in an ambient temperature of max. 40 °C.

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Technical data

#### Standards and operating conditions

Mode			
Product			8400 motec
Conformity			
CE			Low-Voltage Directive
			2006/95/EC
EAC			TP TC 004/2011 (TR C TP TC 020/2011 (TR C
Approval			
UL 508C			Power Conversion Equipment (File-No. E170350)
CSA			CSA 22.2 No. 14
Degree of protection			
EN 60529			IP65 ¹)
NEMA 250			Type 4
Climatic conditions			
Storage (EN 60721-3-1)			1K3 (temperature: -30 °C +60 °C)
Transport (EN 60721-3-2)			2K3 (temperature: -30 °C +75 °C)
Operation (EN 60721-3-3)			3K3 (temperature: -30°C +55°C)
Current derating at over 45°C			2.5% / K
Site altitude			
Amsl	H <sub>max</sub>	[m]	4000
Current derating at over 1000 m		[%/1000 m]	5
Vibration resistance			
Transport (EN 60721-3-2)			2M2
Operation (EN 60721-3-3)			3M6
Operation (Germanischer Lloyd)			General conditions: acceleration resistant up to 2 g

Mode	
Product	8400 motec
Supply form	
	Systems with earthed star point (TN and TT systems) Systems with high-resistance or isolated star point (IT systems)
Noise emission	
EN 61800-3	Integrated radio interference suppression measures: conducted, category C1 <sup>2)</sup> Wall mounting: category C2 with a shielded motor cable of up to 20
	m m
Insulation resistance	
EN 61800-5-1	≤ 2000 m amsl overvoltage category III > 2000 m amsl overvoltage category II
Degree of pollution	
EN 61800-5-1	2
Protective insulation of control circuits	
EN 61800-5-1	Safe mains isolation: double/reinforced insulation

 $<sup>^{1)}\,\</sup>mathrm{Not}$  with plug-in or braking resistor modules.  $^{2)}\,\mathrm{Category}\,\mathrm{C2}$  above 4.0 kW.

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#### Rated data 400 V

- The data is valid for operation at 400 V AC.
- Unless otherwise specified, the data refers to the default setting.

Typical motor power						
4-pole asynchronous motor	Р	[kW]	0.37	0.55 1)	0.55	0.75 1)
Product key						
Inverter			E84DVB□37	′14S□□□2□	E84DVB□55	514S□□□2□
Drive Unit			E84DGDV	B37142PS	E84DGDV	B55142PS
Mains voltage range						
	U <sub>AC</sub>	[V]	3/PE <i>A</i>	AC 320 V-0 % 528 V+	-0 %, 45 Hz-0 % 65 H	Iz+0 %
Rated mains current						
	I <sub>N, AC</sub>	[A]	1.3	1.6	1.8	2.2
Rated output current						
	I <sub>N, out</sub>	[A]	1.3	1.6	1.8	2.2
Rated switching frequency						
	f <sub>ch</sub>	[kHz]	8	4	8	4
Output current						
4 kHz	l <sub>out</sub>	[A]	1.3	1.6	1.8	2.2
8 kHz	l <sub>out</sub>	[A]	1.3		1.8	
16 kHz	l <sub>out</sub>	[A]	0.9		1.2	

#### Data for 60 s overload

Max. output current				
	I <sub>max, out</sub>	[A]	2.0	2.7
Overload time				
	t <sub>ol</sub>	[s]	60	0.0
Recovery time				
	t <sub>re</sub>	[s]	12	0.0

#### Data for 3 s overload

Max. short-time output current				
	I <sub>max, out</sub>	[A]	2.6	3.6
Overload time				
	$t_{ol}$	[s]	3	.0
Recovery time				
	t <sub>re</sub>	[s]	1:	2.0

 $<sup>^{1)}</sup>$  Increased rated power operating mode at 40 °C ambient temperature and max. mains voltage of 400 V AC

#### Technical data



#### Rated data 400 V

- The data is valid for operation at 400 V AC.
- Unless otherwise specified, the data refers to the default setting.

Typical motor power						
4-pole asynchronous motor	P	[kW]	0.37	0.551)	0.55	0.75 1)
Product key						
Inverter			E84DVB□3714S□□□2□		E84DVB□55	514S□□□2□
Drive Unit			E84DGDV	'B37142PS	E84DGDV	B55142PS
Power loss						
	P <sub>V</sub>	[kW]	0.026 0.033		33	
Mass						
	m	[kg]	2.6			
Max. cable length						
Shielded motor cable 2)	I <sub>max</sub>	[m]			20	

#### Brake chopper rated data

Rated power, Brake chopper						
	P <sub>N</sub>	[kW]	0.4	0.5	0.6	0.7
Max. output power, Brake chopper						
	P <sub>max, 1</sub>	[kW]	0	.6	0.	8
Min. brake resistance						
	R <sub>min</sub>	[Ω]		180.0		

#### **Dimensions**

Dimensions			
Height	h	[mm]	109
Width	b	[mm]	161
Depth	t	[mm]	241

 <sup>1)</sup> Increased rated power operating mode at 40 °C ambient temperature and max. mains voltage of 400 V AC
 2) Technically possible cable lengths, irrespective of EMC requirements

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#### Rated data 400 V

- The data is valid for operation at 400 V AC.
- Unless otherwise specified, the data refers to the default setting.

Typical motor power						
4-pole asynchronous motor	Р	[kW]	0.75	1.10 1)	1.10	1.50 1)
Product key						
Inverter			E84DVB□75	145□□□2□	E84DVB□11	.245□□□2□
Drive Unit			E84DGDV	B75142PS	E84DGDV	B11242PS
Mains voltage range						
	U <sub>AC</sub>	[V]	3/PE A	AC 320 V-0 % 528 V+	-0 %, 45 Hz-0 % 65 H	Iz+0 %
Rated mains current						
	I <sub>N, AC</sub>	[A]	2.4	2.9	3.2	3.8
Rated output current						
	I <sub>N, out</sub>	[A]	2.4	2.9	3.2	3.8
Rated switching frequency						
	f <sub>ch</sub>	[kHz]	8	4	8	4
Output current						
4 kHz	l <sub>out</sub>	[A]	2.4	2.9	3.2	3.8
8 kHz	l <sub>out</sub>	[A]	2.4		3.2	
16 kHz	l <sub>out</sub>	[A]	1.6		2.1	

#### Data for 60 s overload

Max. output current				
	I <sub>max, out</sub>	[A]	3.6	4.8
Overload time				
	t <sub>ol</sub>	[s]	60	0.0
Recovery time				
	t <sub>re</sub>	[s]	12	0.0

#### Data for 3 s overload

Max. short-time output current				
	I <sub>max, out</sub>	[A]	4.8	6.4
Overload time				
	$t_{ol}$	[s]	3	.0
Recovery time				
	t <sub>re</sub>	[s]	1:	2.0

 $<sup>^{1)}</sup>$  Increased rated power operating mode at 40 °C ambient temperature and max. mains voltage of 400 V AC

#### Technical data



#### Rated data 400 V

- The data is valid for operation at 400 V AC.
- Unless otherwise specified, the data refers to the default setting.

			[G200]			
Typical motor power						
4-pole asynchronous motor	Р	[kW]	0.75	1.10 1)	1.10	1.501)
Product key						
Inverter			E84DVB=7514S===2= E84DVB=1124S===2=		245□□□2□	
Drive Unit			E84DGDV	B75142PS	E84DGDV	B11242PS
Power loss						
	$P_V$	[kW]	0.0	041	0.0	52
Mass						
	m	[kg]	2.6			
Max. cable length						
Shielded motor cable 2)	I <sub>max</sub>	[m]	20			

#### Brake chopper rated data

Rated power, Brake chopper						
	P <sub>N</sub>	[kW]	0.8	0.9	1.1	1.3
Max. output power, Brake chopper						
	P <sub>max, 1</sub>	[kW]	1	.3	1.	.7
Min. brake resistance						
	R <sub>min</sub>	[Ω]	180.0			

#### **Dimensions**

Dimensions			
Height	h	[mm]	109
Width	b	[mm]	161
Depth	t	[mm]	241

 <sup>1)</sup> Increased rated power operating mode at 40 °C ambient temperature and max. mains voltage of 400 V AC
 2) Technically possible cable lengths, irrespective of EMC requirements

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#### Rated data 400 V

- The data is valid for operation at 400 V AC.
- Unless otherwise specified, the data refers to the default setting.

Typical motor power						
4-pole asynchronous motor	Р	[kW]	1.50	2.201)	2.20	3.00 1)
Product key						
Inverter			E84DVB□15	524S□□□2□	E84DVB□22	24S□□□2□
Drive Unit			E84DGDVB15242PS E84DGDVB22242PS			B22242PS
Mains voltage range						
	U <sub>AC</sub>	[V]	3/PE A	AC 320 V-0 % 528 V+	-0 %, 45 Hz-0 % 65 H	Iz+0 %
Rated mains current						
	I <sub>N, AC</sub>	[A]	3.8	4.5	5.6	6.7
Rated output current						
	I <sub>N, out</sub>	[A]	3.9	4.7	5.6	6.7
Rated switching frequency						
	f <sub>ch</sub>	[kHz]	8	4	8	4
Output current						
4 kHz	l <sub>out</sub>	[A]	3.9	4.7	5.6	6.7
8 kHz	l <sub>out</sub>	[A]	3.9		5.6	
16 kHz	l <sub>out</sub>	[A]	2.6		3.7	

#### Data for 60 s overload

Max. output current				
	I <sub>max, out</sub>	[A]	5.9	8.4
Overload time				
	t <sub>ol</sub>	[s]	60	0.0
Recovery time				
	t <sub>re</sub>	[s]	120.0	

#### Data for 3 s overload

Max. short-time output current				
	I <sub>max, out</sub>	[A]	7.8	11.2
Overload time				
	$t_{ol}$	[s]	3.0	
Recovery time				
	t <sub>re</sub>	[s]	12	2.0

 $<sup>^{1)}</sup>$  Increased rated power operating mode at 40 °C ambient temperature and max. mains voltage of 400 V AC

4.3

#### Technical data



#### Rated data 400 V

- The data is valid for operation at 400 V AC.
- Unless otherwise specified, the data refers to the default setting.

			1000 A 100				
Typical motor power							
4-pole asynchronous motor	Р	[kW]	1.50	2.201)	2.20	3.001)	
Product key							
Inverter			E84DVB□15	524S□□□2□	E84DVB□22	E84DVB□2224S□□□2□	
Drive Unit			E84DGDVB15242PS E84DGDVB2224		B22242PS		
Power loss							
	$P_V$	[kW]	0.0	061	0.0	188	
Mass							
	m	[kg]	2	.6	3.	.5	
Max. cable length							
Shielded motor cable 2)	I <sub>max</sub>	[m]		2	0		

#### Brake chopper rated data

Rated power, Brake chopper						
	P <sub>N</sub>	[kW]	1.5	1.8	2.2	2.6
Max. output power, Brake chopper						
	P <sub>max, 1</sub>	[kW]	2.3		3	
Min. brake resistance						
	R <sub>min</sub>	[Ω]	18	0.0	100	0.0

#### **Dimensions**

Dimensions				
Height	h	[mm]	109	135
Width	b	[mm]	161	176
Depth	t	[mm]	241	261

 <sup>1)</sup> Increased rated power operating mode at 40 °C ambient temperature and max. mains voltage of 400 V AC
 2) Technically possible cable lengths, irrespective of EMC requirements

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#### Rated data 400 V

- The data is valid for operation at 400 V AC.
- Unless otherwise specified, the data refers to the default setting.

			G. S.			
Typical motor power						
4-pole asynchronous motor	Р	[kW]	3.00	4.00 1)	4.00	5.50 <sup>1)</sup>
Product key						
Inverter			E84DVB□30	)24S□□□2□	E84DVB□40	)24S□□□2□
Drive Unit			E84DGDV	B30242PS	E84DGDV	B40242PS
Mains voltage range						
	U <sub>AC</sub>	[V]	3/PE <i>A</i>	AC 320 V-0 % 528 V+	-0 %, 45 Hz-0 % 65 H	lz+0 %
Rated mains current						
	I <sub>N, AC</sub>	[A]	7.2	8.6	9.3	11.1
Rated output current						
	I <sub>N, out</sub>	[A]	7.3	8.7	9.5	11.4
Rated switching frequency						
	f <sub>ch</sub>	[kHz]	8	4	8	4
Output current						
4 kHz	l <sub>out</sub>	[A]	7.3	8.7	9.5	11.4
8 kHz	l <sub>out</sub>	[A]	7.3		9.5	
16 kHz	l <sub>out</sub>	[A]	4.9		6.3	

#### Data for 60 s overload

Max. output current				
	I <sub>max, out</sub>	[A]	11.0	14.3
Overload time				
	t <sub>ol</sub>	[s]	60	0.0
Recovery time				
	t <sub>re</sub>	[s]	120.0	

#### Data for 3 s overload

Max. short-time output current				
	I <sub>max, out</sub>	[A]	14.6	19.0
Overload time				
	t <sub>ol</sub>	[s]	3	.0
Recovery time				
	t <sub>re</sub>	[s]	1:	2.0

 $<sup>^{1)}</sup>$  Increased rated power operating mode at 40 °C ambient temperature and max. mains voltage of 400 V AC

#### Technical data

#### Rated data 400 V

- The data is valid for operation at 400 V AC.
- Unless otherwise specified, the data refers to the default setting.

			(4.2)		37	
Typical motor power						
4-pole asynchronous motor	Р	[kW]	3.00	4.00 1)	4.00	5.50 1)
Product key						
Inverter			E84DVB□3024S□□□2□		E84DVB□4024S□□□2□	
Drive Unit			E84DGDV	'B30242PS	E84DGDVB40242PS	
Power loss					1	
	$P_V$	[kW]	0.	11	0.14	
Mass						
	m	[kg]	3	.5	5	.3
Max. cable length						
Shielded motor cable 2)	I <sub>max</sub>	[m]	20			

#### Brake chopper rated data

Rated power, Brake chopper				
	P <sub>N</sub>	[kW]	3.0	4.0
Max. output power, Brake chopper				
	P <sub>max, 1</sub>	[kW]	4.5	5.5
Min. brake resistance				
	R <sub>min</sub>	[Ω]	100.0	47.0

#### Dimensions

Dimensions				
Height	h	[mm]	135	176
Width	b	[mm]	176	195
Depth	t	[mm]	261	325

Increased rated power operating mode at 40 °C ambient temperature and max. mains voltage of 400 V AC
 Technically possible cable lengths, irrespective of EMC requirements

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#### Rated data 400 V

- The data is valid for operation at 400 V AC.
- Unless otherwise specified, the data refers to the default setting.

Typical motor power						
4-pole asynchronous motor	Р	[kW]	5.50	7.501)	7.50	9.201)
Product key						
Inverter			E84DVB=5524S===2==============================			524S□□□2□
Drive Unit			E84DGDVB55242PS E84DGDVB75242PS			B75242PS
Mains voltage range						
	U <sub>AC</sub>	[V]	3/PE AC 320 V-0 % 528 V+0 %, 45 Hz-0 % 65 Hz+0 %			
Rated mains current						
	I <sub>N, AC</sub>	[A]	12.8	15.3	16.3	19.5
Rated output current						
	I <sub>N, out</sub>	[A]	13.0	15.6	16.5	19.8
Rated switching frequency						
	f <sub>ch</sub>	[kHz]	8	4	8	4
Output current						
4 kHz	l <sub>out</sub>	[A]	13.0	15.6	16.5	19.8
8 kHz	l <sub>out</sub>	[A]	13.0		16.5	
16 kHz	l <sub>out</sub>	[A]	8.6		10.9	

#### Data for 60 s overload

Max. output current					
	I <sub>max, out</sub>	[A]	19.5	24.7	
Overload time					
	t <sub>ol</sub>	[s]	60	60.0	
Recovery time					
	t <sub>re</sub>	[s]	120.0		

#### Data for 3 s overload

Max. short-time output current					
	I <sub>max, out</sub>	[A]	26.0	33.0	
Overload time					
	t <sub>ol</sub>	[s]	3	3.0	
Recovery time					
	$t_{re}$	[s]	12	2.0	

 $<sup>^{1)}</sup>$  Increased rated power operating mode at 40 °C ambient temperature and max. mains voltage of 400 V AC

#### Technical data

#### Rated data 400 V

- The data is valid for operation at 400 V AC.
- Unless otherwise specified, the data refers to the default setting.

Typical motor power						
4-pole asynchronous motor	P	[kW]	5.50	7.50 <sup>1)</sup>	7.50	9.20 1)
Product key						
Inverter			E84DVB = 5524S = = = = = = = = = = = = = = = = = = =		245□□□2□	
Drive Unit			E84DGDVB55242PS E84DGDVB75242PS		B75242PS	
Power loss						
	P <sub>V</sub>	[kW]	0.18 0.23			
Mass						
	m	[kg]	5.3			
Max. cable length						
Shielded motor cable	I <sub>max</sub>	[m]	20			

#### Brake chopper rated data

Rated power, Brake chopper						
	P <sub>N</sub>	[kW]	5.5	6.6	7.5	9.2
Max. output power, Brake chopper						
	P <sub>max, 1</sub>	[kW]	7	5	9.	2
Min. brake resistance						
	R <sub>min</sub>	[Ω]	47.0			

#### Dimensions

Dimensions			
Height	h	[mm]	176
Width	b	[mm]	195
Depth	t	[mm]	325

Increased rated power operating mode at 40 °C ambient temperature and max. mains voltage of 400 V AC
 Technically possible cable lengths, irrespective of EMC requirements

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#### The three units

As a drive package, the Inverter Drives 8400 motec is supplied preinstalled on the geared motor. If the 8400 motec is ordered separately, it is easy to install on the motor or the wall using just four screws. The flexibility offered by the 8400 motec is underlined by its modular and cleverly designed structure, consisting of the "drive unit", "communication unit" and "wiring unit" modules.

If the 8400 motec is ordered individually, the various "units" to be supplied can be selected separately. Details on the functions of the individual units:

#### **Drive unit**

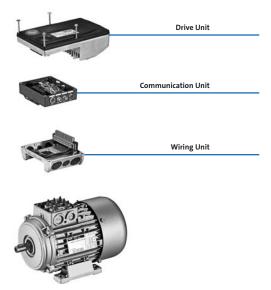
- · Inverter power section
- Easy commissioning via DIP switch, potentiometer or diagnosis terminal
- An easily changeable memory module
- A large LED display to show statuses

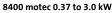
#### **Communication unit**

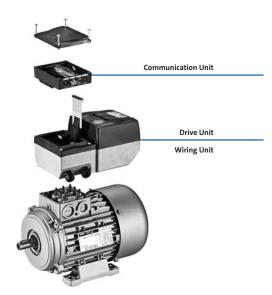
- Interface for I/Os and fieldbus links
- AS-Interface, CANopen, EtherCAT®, EtherNet/IP, PROFIBUS or PROFINET
- I/Os and on-board safety
- Pluggable M12 connection system

#### Wiring Unit

- Connections to the mains and to the drive
- Flexible connection options such as cable glands and diverse plugin connectors
- Connection for brake resistor
- Connection for spring-applied brake





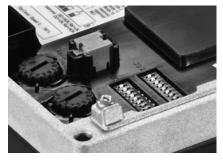


8400 motec 4.0 to 7.5 kW

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#### **Drive Unit**

Alongside the power section, the underside of the drive unit also houses several DIP switches and potentiometers, with which the inverter can easily be commissioned. These allow the configuration, speed and ramp to be adjusted. The drive can, for example, then be quickly and easily adapted to match the system.



Dip switches on Drive Unit

For the purpose of diagnostics, you can plug in a diagnostic adapter alongside the status display without having to disassemble the drive. Thanks to the potentiometer that can be accessed from above, you can make speed settings while the motor is actually running.



Drive Unit diagnostic terminal



Drive Unit diagnostic terminal

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### (LEO)

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#### **Communication Unit**

The communication modules support the following functions:

- · Control of the inverter via digital and analog signals
- · Control of the inverter via the fieldbus systems
- Support for the "safe torque off" functionality
- Connection options for sensors and actuators
- The sensors can be powered by the internal 24 V supply
- Connection options via cable glands and M12 connectors. A total
  of up to 8 screwed connections / plugs can be used. Based on their
  function, the individual communication units are equipped with
  the corresponding connections as standard.

#### Designs

- Basic I/O
- Standard I/O
- Extended-I/O
- AS-i
- CANopen
- EtherCAT®
- EtherNet/IP
- PROFIBUS
- PROFINET

#### **Wiring Unit**

The wiring unit forms the interface between the various motor frame sizes and inverters. In addition to this, it provides the flexibility in terms of connection options for power, motor, brake and brake resistance.

The wiring unit also acts as a holder for various additional modules such as :

- · Wall mounting
- Q5/0 plug-in module as Q5/0 plug connection or loop-through connection
- Q4/2 plug-in module as Q4/2 plug connection or loop-through connection
- Q8/0 plug-in module as Q8/0 plug connection for the motor when wall mounted
- Integrated brake resistor for braking operation via the integrated brake chopper



**Communication Unit** 



Wiring Unit

4.2

Technical data



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#### Technical data



#### **Mains connection**

- ▶ The mains fuse and cable cross-section specifications are for a mains connection of 3 x 400 V.
- Class gG/gl fuses or class gRL semiconductor fuses.
- The cable cross-sections apply to PVC-insulated copper cables.
   Use for installation with UL-approved cables, fuses and brackets.

Typical mo- tor power	Mains voltage	Product key	Circuit breaker	Fuse		Mains connection
4-pole asyn- chronous motor		Inverter		EN 60204-1	UL	Cross-section (without mains choke)
P	U <sub>AC</sub>		1	I	I	q
[kW]	[V]		[A]	[A]	[A]	[mm2]
0.37		E84DVB\[ \]3714S\[ \]\[ \]\[ \]				
0.55	3 AC 320	E84DVB = 5514S = = = 2 = =	C16	16	15	2.5
0.75		E84DVB = 7514S = = = 2 = =				
1.10		E84DVB□1124S□□□2□				
1.50		E84DVB□1524S□□□2□				
2.20	528	E84DVB□2224S□□□2□				
3.00		E84DVB□3024S□□□2□				
4.00		E84DVB□4024S□□□2□	C20		20	4.0
5.50		E84DVB□5524S□□□2□		20		
7.50		E84DVB□7524S□□□2□				

#### **Motor connection**

- ► Keep motor cables as short as possible, as this has a positive effect on the drive behaviour.
- With group drives (multiple motors on one inverter), the resulting cable length is the key factor. This can be calculated using the hardware manual.
- Electric strength of the motor cable: 1 kV as per VDE 250-1.

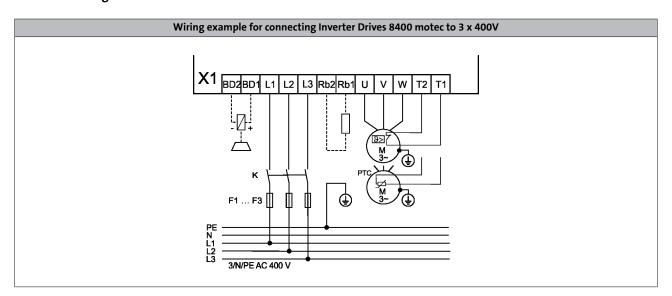
Typical mo- tor power	Mains voltage	Product key Max. cable length		
4-pole asynchron- ous motor		Inverter	shielded C2 without external measures	shielded C2 with external measures
Р	U <sub>AC</sub>		I <sub>max</sub>	I <sub>max</sub>
[kW]	[V]		[m]	[m]
0.37		E84DVB\[ 3714S\[ \] \[ \] \[ 2\[ \]		
0.55		E84DVB□5514S□□□2□		
0.75		E84DVB = 7514S = = = 2 = =		
1.10		E84DVB□1124S□□□2□		
1.50	3 AC 320	E84DVB□1524S□□□2□	20	20
2.20	528	E84DVB□2224S□□□2□	20	20
3.00		E84DVB□3024S□□□2□		
4.00		E84DVB□4024S□□□2□		
5.50		E84DVB□5524S□□□2□		
7.50		E84DVB□7524S□□□2□		

Technical data



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#### **Connection diagrams**



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#### Control connections: Standard I/O

Mode				
Product	8400 motec			
Analog inputs				
Number	1 Switchable: voltage or current input			
Resolution	10 bits			
Value range	0 10 V, 0/4 20 mA			
Digital inputs				
Number	6 (5 + 1 controller enable)			
Switching level	PLC (IEC 61131-2)			
Max. input current	11 mA			
Function				
Digital outputs				
Number	1			
Switching level	PLC (IEC 61131-2)			
Max. output current	50 mA			
Relay				
Number	1			
Contact	NO contact			
AC connection	250V, 3A			
DC connection	24 V, 2 A 240 V, 0.16 A			
External 24 V DC supply				
	To support communication when the 400 V is switched off			
Internal 24 V DC supply	Max. 100 mA for inputs/outputs and sensor feeds			
Interfaces				
CANopen				
Extensions	Fieldbus via communication unit			
Safety engineering	1 safe input for passive/active actuators			
Drive interface				
Encoder input	Via 2 digital inputs, HTL, 2-track, 10 kHz			

#### **Additional connections**

All connections are generally connected internally to terminals. The most common connections of the Communication Unit already have plug connectors. If additional connections are to be implemented, these can be designed as standard PG glands.

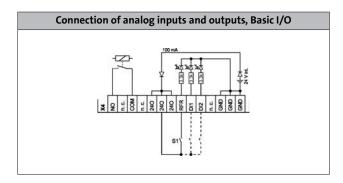
12

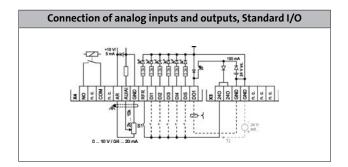
Technical data



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#### **Control connections**





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Technical data



# Inverter Drives 8400 motec

Modules



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# Memory module

All drive settings for the 8400 are stored on the memory module, which is a pluggable memory chip. The memory module ensures that drives can be replaced quickly and without errors being made.

Mode	Features	Product key
Memory module	For 8400 BaseLine, 8400 motec     Packaging unit: 12 items	E84AYM20S/M

# Safety engineering

The "safe torque off (STO)" safety function can be integrated into the Communication Unit in addition to the communication module. This combination is available with any bus.

Communication module	AS-Interface STO	CANopen STO	EtherCAT STO	EtherNet/IP STO	PROFIBUS STO	PROFINET STO					
Certification											
EN ISO 13849-1		PLe									
		Category 4									
EN 61800-5-2		SIL 3									
EN 62061		SIL 3									
IEC 61508		SIL 3									
Fail-safe state											
		Safe torque off									

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#### **Communication modules**

Various communication modules can be installed in the communication unit. They serve to connect the L-force Inverter Drives 8400 motec to a bus system.

#### Overview

	Controller en- able	Digital inputs	Digital outputs	Relay outputs	Analog inputs	Safety STO	External 24 V DC supply
Communication module	Number	Number	Number	Number	Number	Number	Number
Basic I/O	1	2		1			
Standard I/O	1	5	1	1	1		
AS-Interface	1	5	1				
Extended-I/O							
AS-Interface STO	1	5	1	1	1	1	
CANopen	1	5	1				
CANopen STO	1	5	1	1	1	1	
EtherCAT	1	5	1				1
EtherCAT STO	1	5	1	1	1	1	1
EtherNet/IP	1	5	1				1
EtherNet/IPSTO	1	5	1	1	1	1	1
PROFIBUS	1	5	1				1
PROFIBUS STO	1	5	1	1	1	1	1
PROFINET	1	5	1				1
PROFINET STO	1	5	1	1	1	1	1

<sup>►</sup> STO: Safe Torque Off

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#### Communication modules without fieldbus link

The following modules are available for controlling the 8400 motec via digital signals:

- Basic I/O
- Standard I/O
- Extended-I/O

The Basic I/O function module provides the inverter with a minimum number of digital inputs and outputs for the most basic applications.

The Standard I/O function module provides the inverter with an extended number of digital inputs and outputs and is primarily intended for standard applications.

The Extended-I/O function module provides the inverter with one additional digital input and output over the Standard I/O and is intended for use with more complex applications.



Basic I/O, Standard I/O or Extended-IO

Mode		Features	Number of free slots	Product key
Communication module				
Basic I/O	10000	<ul><li> 2 digital inputs</li><li> Controller enable</li><li> 1 relay</li></ul>	8	E84DGFCN□NP
Standard I/O		<ul> <li>Controller enable</li> <li>5 digital inputs</li> <li>1 digital output</li> <li>1 analog input</li> <li>1 relay</li> </ul>	8	E84DGFCS□NP
Extended-I/O		<ul> <li>Controller enable</li> <li>6 digital inputs</li> <li>1 digital output</li> <li>2 analogue inputs (-10/0 to 10 V or 0/4 to 20 mA)</li> <li>1 relay</li> </ul>	8	E84DGFCX□JP

#### Standards and operating conditions

Product key							
			E84DGFCN□NP	E84DGFCS□NP	E84DGFCX□JP		
Mode							
Communication module			Basic I/O	Standard I/O	Extended-I/O		
Degree of protection							
EN 60529			IP65				
Climatic conditions							
Storage (EN 60721-3-1)			1K3	(temperature: -30 °C +6	0 °C)		
Operation (EN 60721-3-3)			3K3 (temperature: -30°C +55°C)				
Transport (EN 60721-3-2)			2K3 (temperature: -30 °C +75 °C)				
Insulation voltage to reference earth/PE							
EN 61800-5-1	U <sub>AC</sub>	[V]	50.0				

#### Pin assignment

In the case of the communication modules without fieldbus connection, only the variant "I/O terminal" is provided. It is connected by means of the cable gland.

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# Communication module: AS-Interface (AS-i)

The AS-Interface communication module enables you to control the 8400 motec using digital control signals. The AS-i bus system has become the established solution for transferring digital signals on the lowest field level. It is designed for applications that do not require the use of powerful fieldbus systems.

The advantages of this system are:

- · Easy handling and commissioning
- Less wiring effort
- Can be easily integrated into existing systems
- Cost reductions



Communication module: AS-Interface (AS-i)

Mode		Features	Number of free slots	Product key
Communication module				
AS-Interface	O EE	<ul> <li>Acyclical polling of diagnostic data</li> <li>Acyclical reading and writing of parameter sets</li> <li>Cyclical drive control</li> <li>Cyclical reading and writing of individual parameters</li> <li>Controller enable</li> <li>5 digital inputs</li> <li>1 digital output</li> <li>4 digital inputs for when power is supplied via the AS-i bus and there is no mains supply</li> </ul>	6	E84DGFCA□NP
AS-Interface STO		<ul> <li>Acyclical polling of diagnostic data</li> <li>Acyclical reading and writing of parameter sets</li> <li>Cyclical drive control</li> <li>Cyclical reading and writing of individual parameters</li> <li>Controller enable</li> <li>5 digital inputs</li> <li>1 digital output</li> <li>4 digital inputs for when power is supplied via the AS-i bus and there is no mains supply</li> <li>1 analog input</li> <li>1 relay</li> <li>Safety function STO</li> </ul>	6	E84DGFCA□JP

#### Standards and operating conditions

Product key					
			E84DGFCA□NP	E84DGFCA□JP	
Mode					
Communication module			AS-Interface	AS-Interface STO	
Degree of protection					
EN 60529			IP65		
Climatic conditions					
Storage (EN 60721-3-1)			1K3 (temperature	e: -30 °C +60 °C)	
Operation (EN 60721-3-3)			3K3 (temperature: -30°C +55°C)		
Transport (EN 60721-3-2)			2K3 (temperature: -30 °C +75 °C)		
Insulation voltage to reference earth/PE					
EN 61800-5-1	U <sub>AC</sub>	[V]	50	0.0	

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# Communication module: AS-Interface (AS-i)

#### **Technical data**

Product key					
Communication module			E84DGFCA□NP	E84DGFCA□JP	
Standard					
			EN 50295 / IEC 62026-2		
Communication					
Communication profile			AS-Interface V3.0		
Medium			2-wire cable for data and auxiliary po	wer	
Network topology					
			Free topology (line, ring, tree, star)		
Node					
			Slave (single or dual)		
			max. 31 standard slaves or safe slaves Max. 62 A/B Slaves		
Number of bus nodes					
			1 31		
Max. cable length					
per bus segment	I <sub>max</sub>	[m]	100 without repeaters / extenders		
			300 including 2 repeaters / extenders		
D 1 1			500 only for star-shaped mains include	ding repeaters / extenders	
Baud rate					
		[kBit/s]	167 (gross value) 53 (net with data transfer efficiency =	= 32%)	
Rated voltage					
DC	U <sub>N, DC</sub>	[V]	24.0		

#### Pin assignment

Can be quickly connected to the bus and certain inputs/outputs via 5-pin M12 connector of the Communication Unit.

The connector is A-coded and can be connected using an AS-i cable featuring penetration technology.

Mode	Variant	Product key		Slot						
Communication module	Communica- tion module		A1	A2	А3	A4	B1	B2	В3	B4
	I/O terminal	E84DGFCAANP								
AS-Interface		E84DGFCA9NP	LED	ASi	DI1 DI2	DI3 DI4				
	I/O terminal	E84DGFCAAJP	LED	ASI						
AS-Interface STO	I/O 2xM12	E84DGFCA9JP			DI1 DI2	DI3 DI4				

► DI1 to DI4= digital inputs

► LED= status display for bus communication

CEOO!

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# **Communication module: CANopen**

The CANopen communication module allows you to control the 8400 motec by sending digital control signals via the "CANopen" bus system.

The advantages of this system are:

- Straightforward, yet extremely powerful, bus system
- Cost-effective
- Easy system integration, as there is a wide range of sensors and actuators available on the market



Communication module: CANopen

Mode	Features	Number of free slots	Product key
Communication module			
CANopen	<ul> <li>Addressing via DIP switches or parameters</li> <li>Internal 24 V DC supply</li> <li>Controller enable</li> <li>5 digital inputs</li> <li>1 digital output</li> </ul>	6	E84DGFCC□NP
CANopen STO	<ul> <li>Addressing via DIP switches or parameters</li> <li>Internal 24 V DC supply</li> <li>Controller enable</li> <li>5 digital inputs</li> <li>1 digital output</li> <li>1 analog input</li> <li>1 relay</li> <li>Safety function STO</li> </ul>	6	E84DGFCC□JP

#### Standards and operating conditions

Product key					
			E84DGFCC□NP	E84DGFCC□JP	
Mode					
Communication module			CANopen	CANopen STO	
Degree of protection					
EN 60529			IP65		
Climatic conditions					
Storage (EN 60721-3-1)			1K3 (temperature	e: -30 °C +60 °C)	
Operation (EN 60721-3-3)			3K3 (temperature	e: -30°C +55°C)	
Transport (EN 60721-3-2)			2K3 (temperature: -30 °C +75 °C)		
Insulation voltage to reference earth/PE					
EN 61800-5-1	$U_AC$	[V]	50.0		

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# **Communication module: CANopen**

#### **Technical data**

Product key						
Communication module			E84DGFCC□NP	E84DGFCC□JP		
Communication						
Medium			DIN ISO 11898			
Communication profile			CANopen, DS301 V4.02 Lenze system bus			
Baud rate						
	b	[kBit/s]	20 50 125 250 500 800 1000			
Node						
			Slave Multi-master			
Network topology						
			Line with terminating resistors (120 ohm) at both ends			
Number of logical process data channels			2 "send" PDOs and 2 "receive" PDOs (each with 1 - 8 bytes)			
Number of logic parameter data channels				,		
			Max. 2 server SDO channels (with 1 -	8 bytes)		
Number of bus nodes						
			63			
Max. cable length						
per bus segment	I <sub>max</sub>	[m]	17 for 1000 kbps 40 for 800 kbps 110 for 500 kbps 290 for 250 kbps 630 for 125 kbps 1500 for 50 kbps 3900 for 20 kbps 8000 for 10 kbps			
Rated voltage						
DC	U <sub>N, DC</sub>	[V]	24.0			

### Pin assignment

Can be quickly connected to the bus and certain inputs/outputs via 5-pin M12 connector of the Communication Unit.

The connector is A-coded and can be connected using a 5-pole connection M12.

Mode	Variant	Product key	Slot							
Communication module	Communica- tion module		A1	A2	А3	A4	B1	B2	В3	B4
	I/O terminal	E84DGFCCANP								
CANopen	I/O 2xM12	E84DGFCC9NP	DI1 DI2	CAN-in	CAN-	DI3 DI4				
	I/O terminal	E84DGFCCAJP		CAIN-III	out					
CANopen STO	I/O 2xM12	E84DGFCC9JP	DI1 DI2			DI3 DI4				

► DI1 to DI4= digital inputs

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#### EtherCAT® communication module

With the EtherCAT® communication module, the Inverter Drives 8400 motec supports end-to-end communication from the field level right through to company management level.

The benefits of this system include:

- Fieldbus system capable of handling large data volumes
- Use of IT standards
- Integrated switch allows direct looping of EtherCAT via the inverters
- Integrated I/O node. Capable of communication and reading inputs even when the 400V supply us switched off.
- · Option to connect an external 24V supply



EtherCAT® communication module

Mode		Features	Number of free slots	Product key
Communication module				
EtherCAT	7	Support for the "Distributed clocks" (DC) functionality for synchronisation via fieldbus Link / Activity PDO transfer with CoE (CANopen over EtherCAT) Cycle times: 1 ms or a whole multiple of 1 ms; maximum 15 ms when using "distributed clocks" (DC) LEDs for status display Controller enable Sigital inputs I digital output	5	E84DGFCT□NP
EtherCAT STO	To the state of th	Support for the "Distributed clocks" (DC) functionality for synchronisation via fieldbus Link / Activity PDO transfer with CoE (CANopen over EtherCAT) Cycle times: 1 ms or a whole multiple of 1 ms; maximum 15 ms when using "distributed clocks" (DC) LEDs for status display Controller enable digital inputs 1 digital output 1 analog input 1 relay Safety function STO	5	E84DGFCT□JP

### Standards and operating conditions

Product key						
			E84DGFCT□NP	E84DGFCT□JP		
Mode						
Communication module			EtherCAT	EtherCAT STO		
Degree of protection						
EN 60529			IP65			
Climatic conditions						
Storage (EN 60721-3-1)			1K3 (temperature	e: -30 °C +60 °C)		
Operation (EN 60721-3-3)			3K3 (temperature	e: -30°C +55°C)		
Transport (EN 60721-3-2)			2K3 (temperature: -30 °C +75 °C)			
Insulation voltage to reference earth/PE						
EN 61800-5-1	U <sub>AC</sub>	[V]	50	0.0		

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### EtherCAT® communication module

#### **Technical data**

Product key				
Communication module			E84DGFCT□NP	E84DGFCT□JP
Communication				
Medium			CAT5e S/FTP according to ISO/ICE118	01 (2002)
Communication profile			CoE (CANopen over EtherCAT)	
Baud rate				
	b	[MBit/s]	100	
Node				
			Slave	
Network topology				
			Line Switch	
Number of logical process data channels				
			1	
Process data words (PCD)				
to the master			1 10 (max. 20 bytes, 16 bits/word)	
from the master			1 8 (max. 16 bytes, 16 bits/word)	
Parameter data				
Max. mailbox size for CoE transfer		[Byte]	128	
Number of bus nodes				
			Max. 65535	
Max. cable length				
between two nodes	I <sub>max</sub>	[m]	100	
Rated voltage				
DC	U <sub>N, DC</sub>	[V]	24.0	

#### Pin assignment

Can be quickly connected to the bus and certain inputs/outputs via 5-pin M12 connector of the Communication Unit.

The connector is A-coded and can be connected using a 5-pole connection M12.

Mode	Variant	Product key	Slot							
Communication module	Communica- tion module		A1	A2	А3	A4	B1	B2	В3	В4
	I/O terminal	E84DGFCTANP								
EtherCAT	I/O 1xM12	E84DGFCT9NP	LED	EC-in	EC-out	DI1 DI2				
	I/O terminal	E84DGFCTAJP	LED	EC-III	EC-out					
EtherCAT STO	I/O 1xM12	E84DGFCT9JP				DI1 DI2				

▶ DI1 to DI4= digital inputs

► LED= status display for bus communication



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### EtherNet/IP communication module

The EtherNet/IP communication module based on standard TCP and UDP enables the Inverter Dives 8400 motec to support a continuous communication from the field level right through to the controlling system.

The benefits of this system include:

- Currently widespread fieldbus based on real-time Ethernet
- Supports DHCP and BootP in allocating the IP address
- Devices linked via EtherNet/IP can be implemented seamlessly and with minimum configuration expense via mapping into the I/O tree of the RSLogix programming tool



EtherNet/IP communication module

Mode		Features	Number of free slots	Product key
Communication module				
EtherNet/IP	0.535	Supports multicast messages, UCMM, ACD, BOOTP/DHCP, VLAN-Tagging/DSCP Internal 24 V DC supply LEDs for status display Controller enable J digital inputs 1 digital output	5	E84DGFCG□NP
EtherNet/IP STO	O sale	Supports multicast messages, UCMM, ACD, BOOTP/DHCP, VLAN-Tagging/DSCP Internal 24 V DC supply LEDs for status display Controller enable Jdigital inputs I digital output I analog input I relay Safety function STO	5	E84DGFCG□JP

#### Standards and operating conditions

Product key						
			E84DGFCG□NP	E84DGFCG□JP		
Mode						
Communication module			EtherNet/IP	EtherNet/IP STO		
Degree of protection						
EN 60529			IP65			
Climatic conditions						
Storage (EN 60721-3-1)			1K3 (temperature	e: -25 °C +60 °C)		
Operation (EN 60721-3-3)			3K3 (temperature	e: -10°C +55°C)		
Transport (EN 60721-3-2)			2K3 (temperature: -25 °C +70 °C)			
Insulation voltage to reference earth/PE						
EN 61800-5-1	$U_AC$	[V]	50	0.0		

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# EtherNet/IP communication module

#### **Technical data**

Product key				
Communication module			E84DGFCG□NP	E84DGFCG□JP
Communication			E04DGI CG:INI	E84DGI CG
Medium			CAT5e S/FTP according to ISO/ICE11	801 / EN50173
Communication profile			EtherNET/IP, AC Drive	,
Baud rate				
	b	[MBit/s]	10/100 (full duplex/half duplex)	
Node				
			Slave (Adapter)	
Network topology				
			Tree, star and line	
Process data words (PCD)				
16 Bit			1 16	
Number of bus nodes				
			max. 254 im Subnetz	
Max. cable length				
between two nodes	I <sub>max</sub>	[m]	100	
Rated voltage				
DC	U <sub>N, DC</sub>	[V]	24.0	

#### Pin assignment

Can be quickly connected to the bus and certain inputs/outputs via 5-pin M12 connector of the Communication Unit.

The connector is D-coded and can be connected using a 5-pole M12 connection.

Mode	Variant	Product key	Slot							
Communication module	Communica- tion module		A1	A2	А3	A4	B1	B2	В3	В4
	E84DGFCGANP		EN-in	EN-out						
EtherNet/IP	I/O terminal	E84DGFCG9NP LED			DI1 DI2					
		E84DGFCGAJP	LED	EIN-III	EIN-OUL					
EtherNet/IP STO	I/O 1xM12	E84DGFCG9JP				DI1 DI2				

► DI1 to DI4= digital inputs

► LED= status display for bus communication

#### **PROFIBUS communication modules**

When combined with the PROFIBUS communication module, the 8400 motec supports PROFIBUS, the most widely used fieldbus system

The advantages of this system are:

- Widely used and extremely powerful fieldbus system
   Integrated I/O node. Capable of communication and reading inputs even when the 400 V supply is switched off.
- Option of connecting an external 24V supply



**PROFIBUS** communication modules

Mode	Featu	res	Number of free slots	Product key
Communication module				
PROFIBUS	cha • DPV set • Into • 4 LI • Cor • 5 d	VO: basic functionalities such as cyclical data exnege and diagnostics V1: supports acyclical data exchange for parameter ting, operation and alarm handling ernal 24 V DC supply EDs for status display introller enable igital inputs	5	E84DGFCP□NP
PROFIBUS STO	cha - DP' set - Inte - 4 LI - Cor - 5 d - 1 d - 1 a - 1 re	VO: basic functionalities such as cyclical data ex- inge and diagnostics V1: supports acyclical data exchange for parameter ting, operation and alarm handling ernal 24 V DC supply EDs for status display introller enable igital inputs igital output nalog input elay ety function STO	5	E84DGFCP□JP

#### Standards and operating conditions

Product key						
			E84DGFCP□NP	E84DGFCP□JP		
Mode						
Communication module			PROFIBUS	PROFIBUS STO		
Degree of protection						
EN 60529			IP65			
Climatic conditions						
Storage (EN 60721-3-1)			1K3 (temperature	e: -30 °C +60 °C)		
Operation (EN 60721-3-3)			3K3 (temperature	e: -30°C +55°C)		
Transport (EN 60721-3-2)			2K3 (temperature: -30 °C +75 °C)			
Insulation voltage to reference earth/PE						
EN 61800-5-1	U <sub>AC</sub>	[V]	50	0.0		

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#### **PROFIBUS communication modules**

#### **Technical data**

Product key						
Communication module			E84DGFCP□NP	E84DGFCP□JP		
Communication						
Medium			RS 485			
Communication profile			PROFIBUS-DP-V0 (DRIVECOM) PROFIBUS-DP-V1 (PROFIdrive)			
Baud rate						
	b	[kBit/s]	9.6 12 000 (automatic detection)			
Node						
			Slave			
Network topology						
			with repeater: line or tree without repeater: line			
Process data words (PCD)						
16 Bit			18			
DP user data length						
			Optional parameter channel (4 words Acyclic parameter data channel (DP-V	s) + process data words /1): max 240 bytes		
Number of bus nodes						
			31 slaves + 1 master per bus segment With repeaters: 125	:		
Max. cable length						
per bus segment	I <sub>max</sub>	[m]	1200 (depending on the baud rate and the cable type used)			
Rated voltage						
DC	U <sub>N, DC</sub>	[V]	24.0			

# Pin assignment

Can be quickly connected to the bus and certain inputs/outputs via 5-pin M12 connector of the Communication Unit.

The connector is B-codiert coded and can be connected using a 5-pole connection M12.

Mode	Variant	Product key	Slot							
Communication module	Communica- tion module		A1	A2	А3	A4	B1	B2	В3	B4
	I/O terminal E84DGFCPANP									
PROFIBUS	I/O 1xM12	E84DGFCP9NP	LED	DP in	PB-out	DI1 DI2				
	I/O terminal	E84DGFCPAJP	LED	LED PB-in	PB-out					
PROFIBUS STO	I/O 1xM12	E84DGFCP9JP				DI1 DI2				

DI1 to DI4= digital inputs
 LED= status display for bus communication

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Inverter Drives 8400 motec



#### **PROFINET** communication modules

With the PROFINET communication module, the 8400 motec supports a fieldbus system for continuous communication from the field level right through to company management level.

The benefits of this system include:

- Fieldbus system capable of handling large data volumes
- Use of IT standards
- Integrated switch allows direct looping of PROFINET via the invert-
- Integrated I/O node. Capable of communication and reading inputs even when the 400 V supply us switched off.
- Option to connect an external 24 V supply



**PROFINET** communication modules

Mode		Features	Number of free slots	Product key
Communication module				
PROFINET	O SOF	<ul> <li>Automatic detection of the 100 Mbps baud rate</li> <li>Creation of a line topology through integrated 2-port switch</li> <li>Support for I&amp;M 0 to 4 functionality for identification of the standard device</li> <li>Link / Activity</li> <li>4 LEDs for status display</li> <li>Controller enable</li> <li>5 digital inputs</li> <li>1 digital output</li> </ul>	5	E84DGFCR□NP
PROFINET STO	TO ROOM	<ul> <li>Automatic detection of the 100 Mbps baud rate</li> <li>Creation of a line topology through integrated 2-port switch</li> <li>Support for I&amp;M 0 to 4 functionality for identification of the standard device</li> <li>Link / Activity</li> <li>4 LEDs for status display</li> <li>Controller enable</li> <li>5 digital inputs</li> <li>1 digital output</li> <li>1 analog input</li> <li>1 relay</li> <li>Safety function STO</li> </ul>	5	E84DGFCR□JP

#### Standards and operating conditions

Product key						
			E84DGFCR□NP	E84DGFCR□JP		
Mode						
Communication module			PROFINET	PROFINET STO		
Degree of protection						
EN 60529			IP65			
Climatic conditions						
Storage (EN 60721-3-1)			1K3 (temperature	e: -30 °C +60 °C)		
Operation (EN 60721-3-3)			3K3 (temperature	e: -30°C +55°C)		
Transport (EN 60721-3-2)			2K3 (temperature: -30 °C +75 °C)			
Insulation voltage to reference earth/PE						
EN 61800-5-1	U <sub>AC</sub>	[V]	50	0.0		

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#### **PROFINET** communication modules

#### **Technical data**

Product key				
•			50 4D 656D—14D	
Communication module			E84DGFCR□NP	E84DGFCR□JP
Communication				
Medium			CAT5e S/FTP according to ISO/ICE118	01 (2002)
Communication profile			PROFINET RT Conf. Class B	
Baud rate				
	b	[MBit/s]	100	
Node				
			Slave (Device)	
Network topology				
			Tree, star and line	
Number of logical process data channels				
			1	
Process data words (PCD)				
16 Bit			18	
Max. cable length				
between two nodes	I <sub>max</sub>	[m]	100	
Rated voltage				
DC	U <sub>N, DC</sub>	[V]	24.0	

#### Pin assignment

Can be quickly connected to the bus and certain inputs/outputs via 5-pin M12 connector of the Communication Unit.

The connector is D-coded and can be connected using a 5-pole M12 connection.

Mode	Variant	Product key	Slot									
Communication module	Communica- tion module		A1	A2	A3	A4	B1	B2	В3	B4		
	I/O terminal	E84DGFCRANP										
PROFINET	I/O 1xM12	E84DGFCR9NP	LED	PN-in	PN-out	DI1 DI2						
	I/O terminal	E84DGFCRAJP	LED	LED	LED	FIN-III	FIN-OUT					
PROFINET STO	I/O 1xM12	E84DGFCR9JP				DI1 DI2						

- ► DI1 to DI4= digital inputs
- ► LED= status display for bus communication

# Inverter Drives 8400 motec

Modules



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# **Wiring Unit versions**

The wiring unit forms the interface between the various motor frame sizes and inverters. In addition to this, it provides the flexibility in terms of connection options for power, motor, brake and brake resistance. The correct wiring unit is selected based on the size of the motor and the terminal box.



Wiring Unit

Product key	E84DGVN1E	E84DGVN2E	E84DGVN3E	E84DGVN4E	E84DGVN5E
Mode	Wiring Unit				
Features		ı		1	
	• For E84DVB□3714 to 1124 • For motor frame sizes 063 and 071 • Enclosure: IP66	• For E84DVB□5514 to 1524 • For motor frame sizes 080, 090 and 100 • Enclosure: IP66	• For E84DVB□2224 to 3024 • For motor frame sizes 080, 090 100 and 112 • Enclosure: IP66	• For E84DVB□4024 to 7524 • For motor frame sizes 080, 090 100 and 112 • Enclosure: IP66	<ul> <li>For E84DVB□5524 to 7524</li> <li>For motor frame size 132</li> <li>Enclosure: IP66</li> </ul>

#### **Connector modules**

Screwed sockets for the mains connection are included on the Inverter Drives 8400 motec as standard. Alternatively, Q4, Q5 or Q8 plug-in modules can be used. Thanks to the universal connection options offered by the modules, a supply bus can be set up using plugs and couplings without the need for any external accessories.



#### **HAN** connector

Mode		Features	Product key
Plug-in module 1 x Q5/0, left	O CO	• 5 power contacts and PE: 16 A/400 V	E84DZEVBLANP
Plug-in module 1 x Q5/0, right		Applications with external mains distributor	E84DZEVBRANP

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#### **HAN** connector

Mode		Features	Product key
Plug-in module 2 x Q5/0, left		• 5 power contacts and PE: 16 A/400 V	E84DZEVBLAFP
Plug-in module 2 x Q5/0, right		Applications with mains loops	E84DZEVBRAFP
Plug-in module 1 x Q4/2, left		• 4 power contacts and PE: 32 A/400 V	E84DZEVBLPNP
Plug-in module 1 x Q4/2, right		2 control contacts: 10 A/24 V     Applications with external mains distributor	E84DZEVBRPNP
Plug-in module 2 x Q4/2, left	THE STATE OF THE S	<ul> <li>4 power contacts and PE: 32 A/400 V</li> <li>2 control contacts: 10 A/24 V</li> </ul>	E84DZEVBLPRP
Plug-in module 2 x Q4/2, right	F. S.	Applications with mains loops	E84DZEVBRPRP
Plug-in module 1 x Q8/0, left		• 6 power contacts and PE: 25 A/400 V	E84DZEVBLCNP
Plug-in module 1 x Q8/0, right		Motor connection with wall mounting	E84DZEVBRCNP

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#### Internal brake resistor

An internal brake resistor can also be mounted on the  ${\bf right\text{-}hand}$  side of the 8400 motec instead of the plug-in modules.



Internal brake resistor

Typical motor power	Mains voltage	Product ke	ey .	Rated resistance	Rated power	Thermal capa- city
4-pole asyn- chronous motor		Inverter	Brake resistor			
Р	U <sub>AC</sub>			R <sub>N</sub>	$P_{N}$	C <sub>th</sub>
[kW]	[V]			[Ω]	[kW]	[KWs]
0.37		E84DVB□3714S□□□2□			15.0	
0.55		E84DVB□5514S□□□2□		220.0		
0.75		E84DVB□7514S□□□2□	E84DZEW220R			
1.10		E84DVB□1124S□□□2□				
1.50	3 AC 320 528	E84DVB□1524S□□□2□				0.28
2.20	3 AC 320 328	E84DVB□2224S□□□2□	E84DZEW100R	100.0		0.28
3.00		E84DVB□3024S□□□2□	E84DZEVV100K	100.0		
4.00		E84DVB□4024S□□□2□				
5.50		E84DVB□5524S□□□2□	E84DZEW047R	47.0		
7.50		E84DVB□7524S□□□2□				

# Wall mounting

The wall mount is used to attached is the inverter to be machine chassis or the wall. The design offers IP65 protection and is easy to attach.



Wall mounting

Product key	
	E84DZMAWE1
Mode	
	Wall mounting
Features	
	<ul><li>Degree of protection IP65</li><li>Ease of installation</li></ul>

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#### **Brake resistors**

An external brake resistor is required to brake high moments of inertia or in the event of prolonged operation in generator mode; this resistor converts braking energy into heat.

The brake resistors recommended in the table below have been dimensioned for approx. 1.5 times the regenerative power, with a cycle time of 15/135 s (brake/rest ratio). These brake resistors generally meet the usual requirements of standard applications.

The brake resistors are fitted with a thermostat (potential-free NC contact)



**Brake resistor** 

Typical mo- tor power	Mains voltage	Product key		Rated resist- ance	Rated power	Thermal capacity	Dimensions	Mass
4-pole asynchron- ous motor		Inverter	Brake resistor					
Р	U <sub>AC</sub>			R <sub>N</sub>	$P_N$	C <sub>th</sub>	hxbxt	m
[kW]	[V]			[Ω]	[kW]	[KWs]	[mm]	[kg]
0.37		E84DVB□3714S□□□2□						
0.55		E84DVB□5514S□□□2□						
0.75		E84DVB□7514S□□□2□	ERBS180R350W	180.0	350.0	53.0	382 x 124 x 122	2.0
1.10		E84DVB□1124S□□□2□						
1.50	3 AC 320	E84DVB□1524S□□□2□						
2.20	528	E84DVB□2224S□□□2□	ERBS100R625W	100.0	625.0	94.0	566 x 124 x 122	3.0
3.00		E84DVB□3024S□□□2□	EKB3100K623VV	100.0	025.0	94.0	366 X 124 X 122	5.0
4.00		E84DVB□4024S□□□2□	50050 (50 to 100)					
5.50		E84DVB□5524S□□□2□	ERBS047R400W ERBS047R800W	47.0 47.0	400.0 800.0	60.0 120	400 x 110 x 105 710 x 110 x 105	2.3 3.9
7.50		E84DVB□7524S□□□2□			220.0			

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#### **USB** diagnostic adapter

The operation, parameter setting and diagnostics of the Inverter Drives 8400 and the Servo Drives 9400 via the L-force diagnostics is made with the keypad X400 or a PC. The connection of a PC can be made via a USB interface and the USB diagnostic adapter.

For connecting the USB diagnostic adapter with the L-force diagnostics interface (DIAG) tat the inverter, three different connecting cables are separately available in the lengths 2.5 m, 5 m and 10 m. The connection can be established during operation. The engineering tools EASY Starter or Engineer can be used to carry out the operation, parameter setting or diagnostics of the inverters. Both tools have simple intuitive surfaces. This enables a quick and easy commissioning.

Optionally to the USB diagnostic adapter, the PC system bus adapter can be used. For this purpose, a CANopen interface must be available at the inverter.



USB diagnostic adapter incl. connecting cable to the PC

The engineering tools EASY Starter or Engineer are used for operation, parameter setting and diagnostics of the inverters.

Mode	Features	Product key
USB diagnostic adapter	<ul> <li>Input-side voltage supply via USB connection on PC</li> <li>Output-side voltage supply via inverter's diagnostic interface</li> <li>Diagnostic LEDs</li> <li>Electrical isolation of PC and inverter</li> <li>Hot-pluggable</li> </ul>	E94AZCUS

#### Connecting cables for USB diagnostic adapter

Mode	Features	Product key
Connecting cable for USB diagnostic adapter	• Length: 2.5 m	EWL0070
	Length: 5 m	EWL0071
	Length: 10 m	EWL0072

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# **Diagnosis terminal**

The diagnosis terminal can be used as an alternative to a PC if you are looking for an easy way to operate the inverter, set parameters or carry out diagnostics locally. The structured menus and plain text display provide quick access to data.

The diagnosis terminal can be plugged into the inverter's L-force diagnostic interface (DIAG) from the outside.



Diagnosis terminal

Mode	Features	Slot	Product key
Diagnosis terminal	<ul> <li>Diagnosis terminal inside robust housing</li> <li>incl. 2.5 m cable</li> <li>Degree of protection IP20</li> <li>For 8400 motec and protec.</li> </ul>	DIAG	EZAEBK2003

# Switch/potentiometer unit

The switch/potentiometer unit is fitted directly to the 8400 motec or in a different position within the system. An analogue setpoint can be specified with the switch/potentiometer unit and the control connections integrated in the inverter by using the integrated potentiometer; the rotary switch can, for example, be used to start/stop the drive or change the direction of rotation.

The switch/potentiometer unit is supplied with a 2.5 m connection cable



Switch/potentiometer unit

Mode	Product key
Switch/potentiometer unit (IP65)	E82ZBU

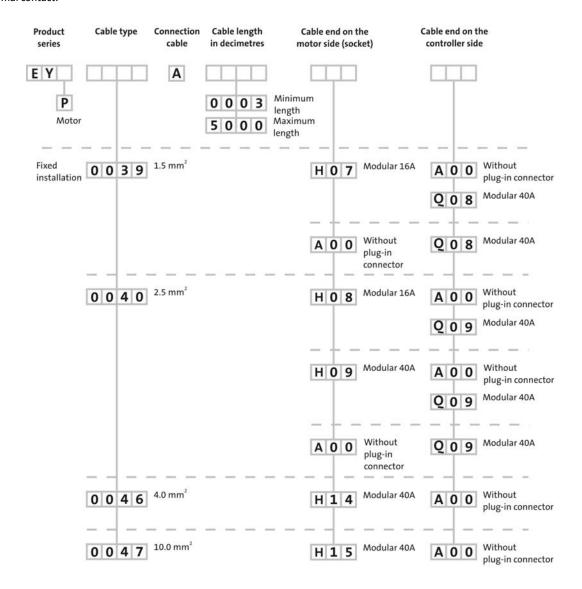
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# System cables

For connection of the motor, Lenze provides finished hybrid cables. They are optimally matched to the connection between the Drive Package components. Motor connection, blower connection, brake connection and temperature monitoring are integrated in the cables. Cables up to a length of 100 m can be selected in increments of 0.1 m

#### 10-pole cables

Available with cross-sections 1.5  $^2$  and 2.5  $^2$  with connection for brake or thermal contact.



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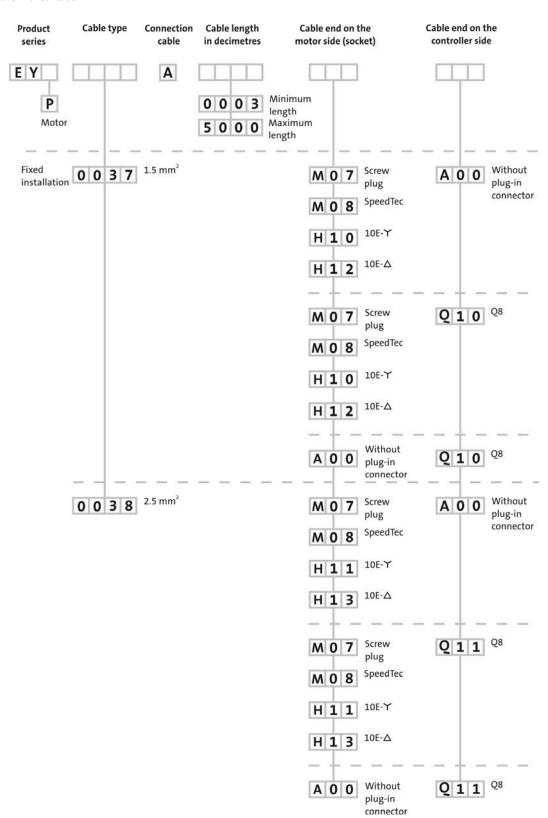
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#### 8-pole cables

Available with cross-sections 1.5 $^2$  and 2.52  $^2$  with connection for brake and thermal contact.



# Inverter Drives 8400 motec

Accessories



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# Inverter Drives 8400 motec

Accessories



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